

A Hard Problem In A Boolean Asynchronous Freezing Cellular Automata

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Ríos-Wilson



Facultad de Ingeniería y Ciencias

International Workshop on Boolean Networks, 9 de enero
de 2020

Cellular automata

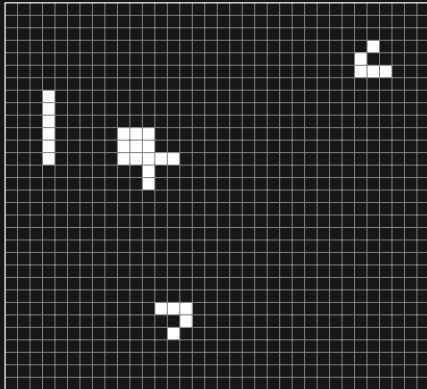
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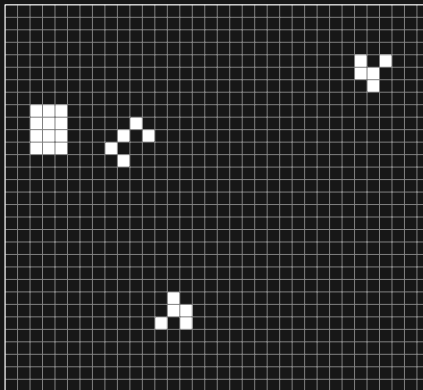
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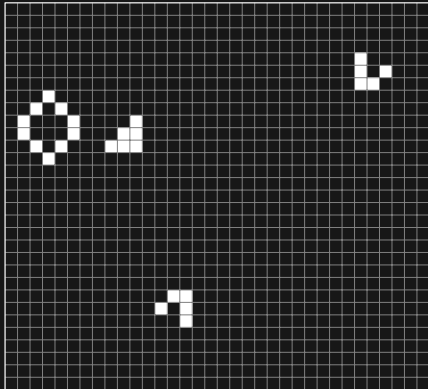
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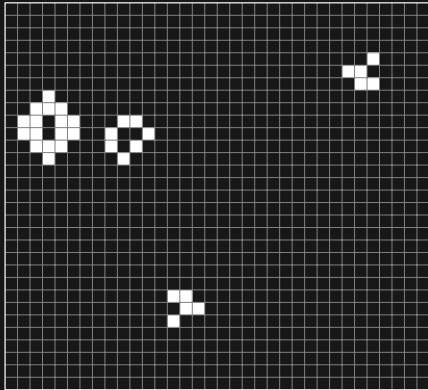
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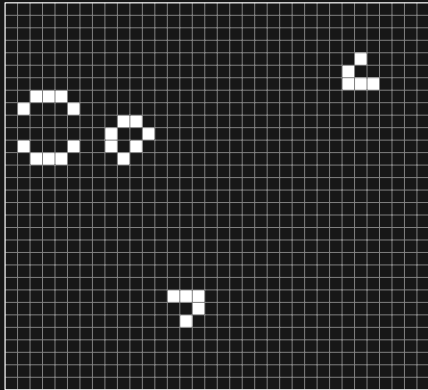
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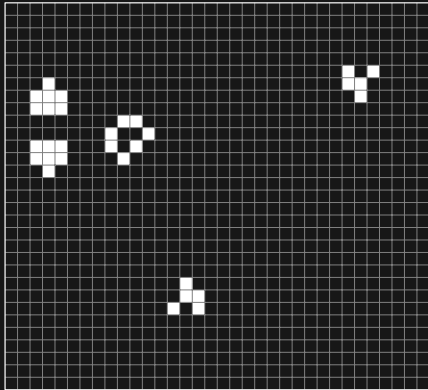
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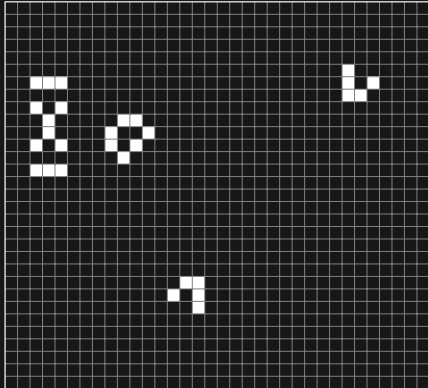
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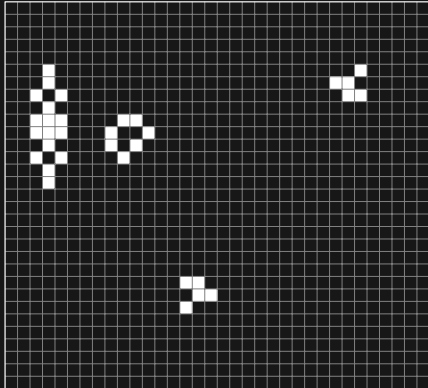
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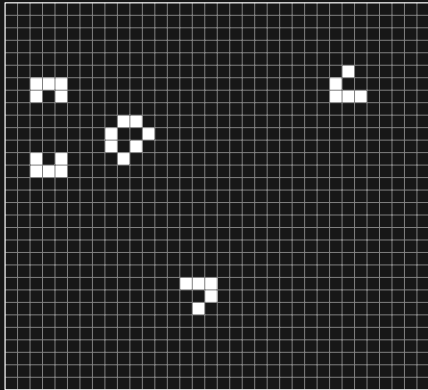
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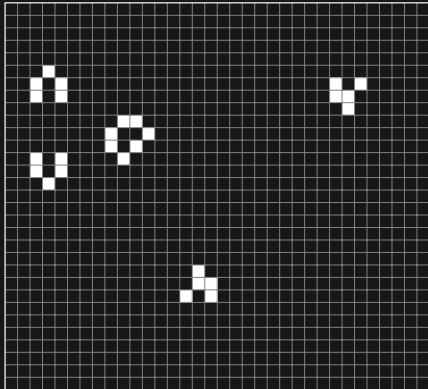
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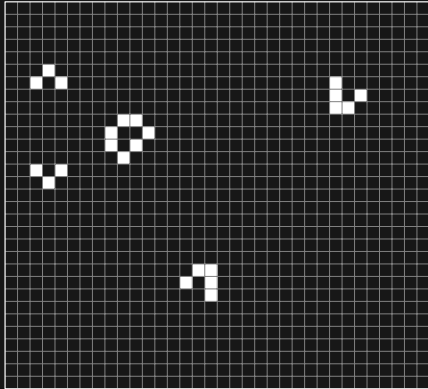
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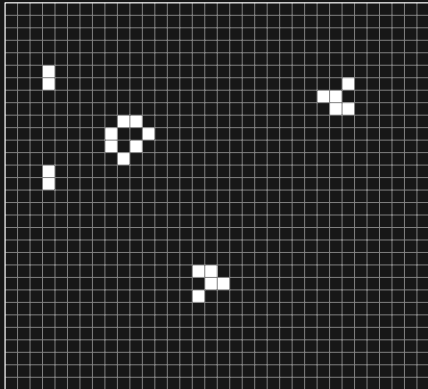
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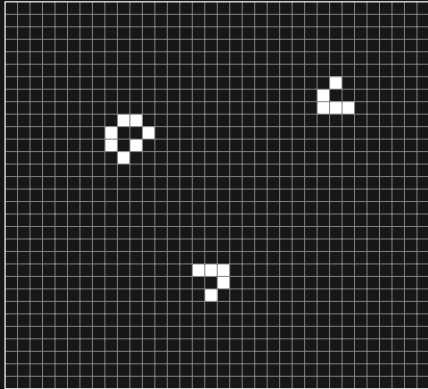
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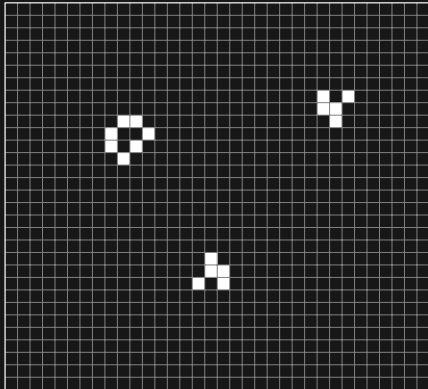
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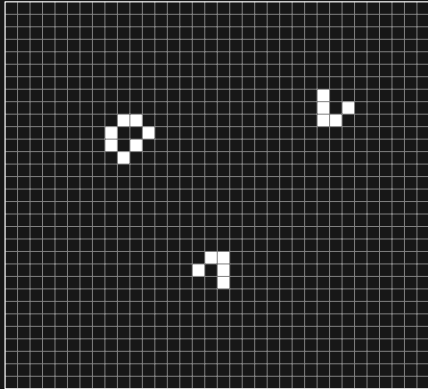
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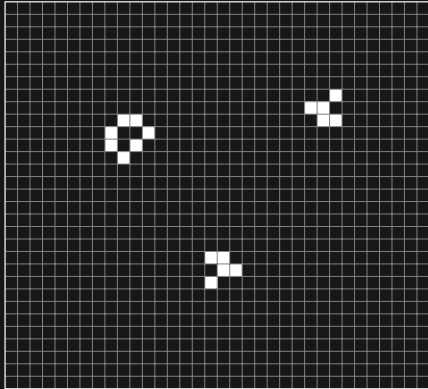
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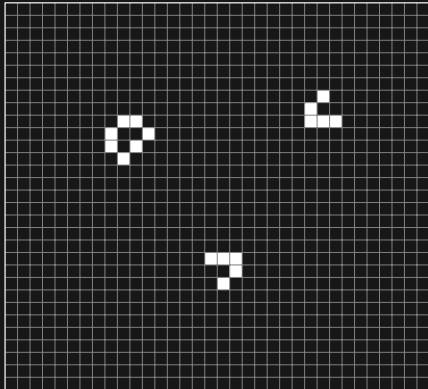
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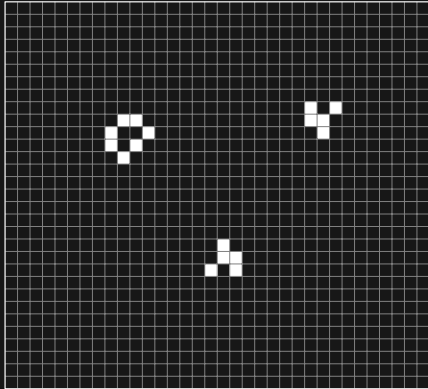
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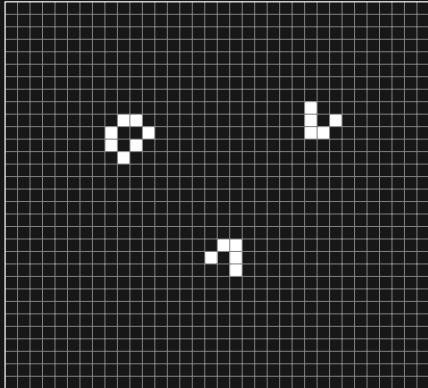
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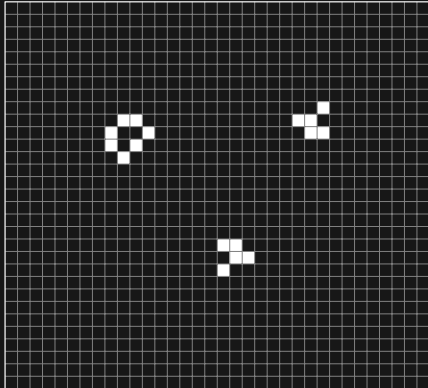
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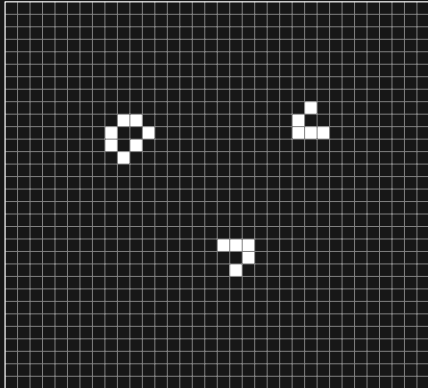
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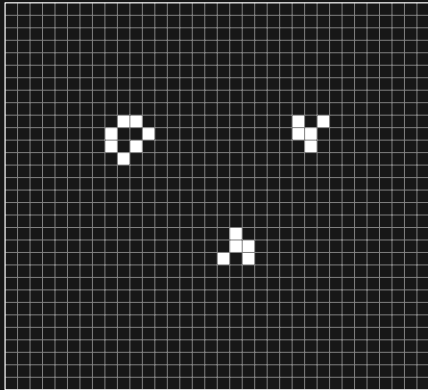
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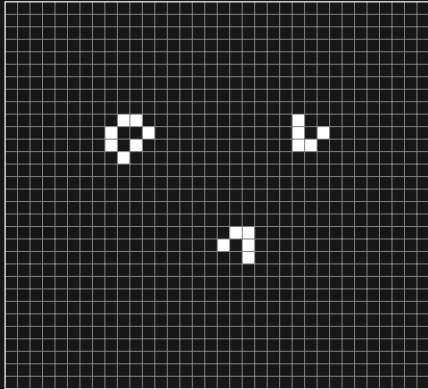
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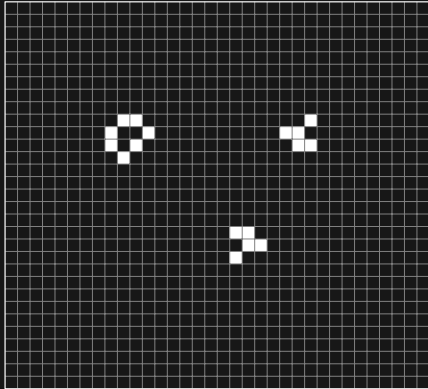
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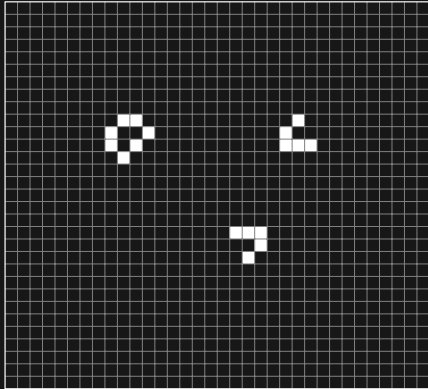
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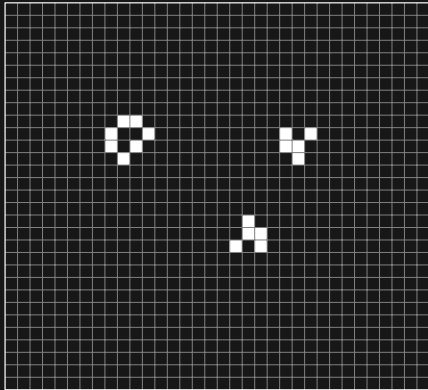
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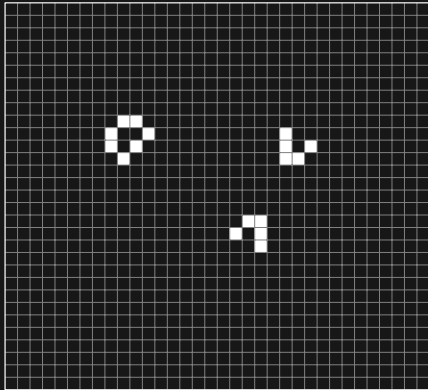
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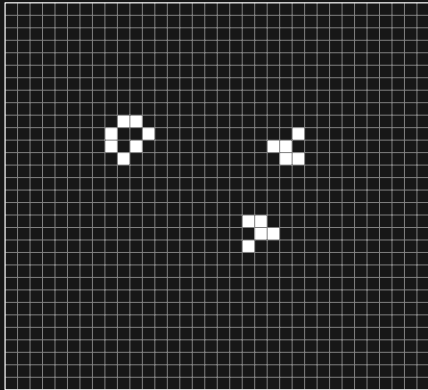
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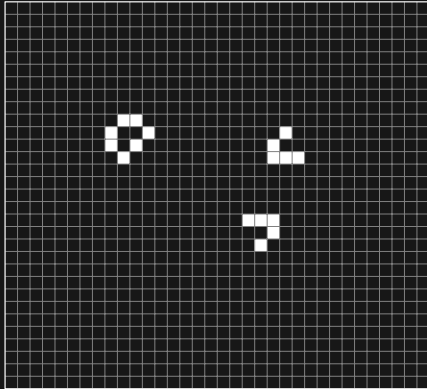
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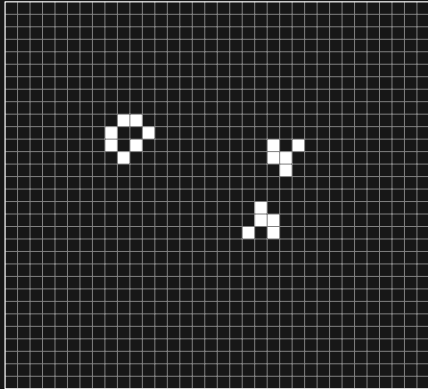
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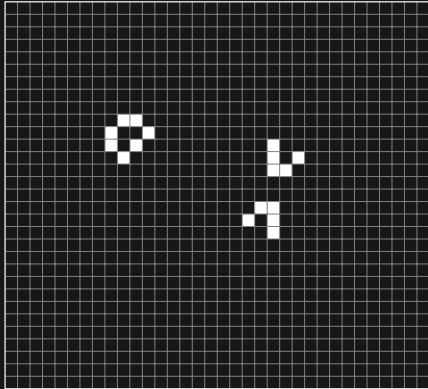
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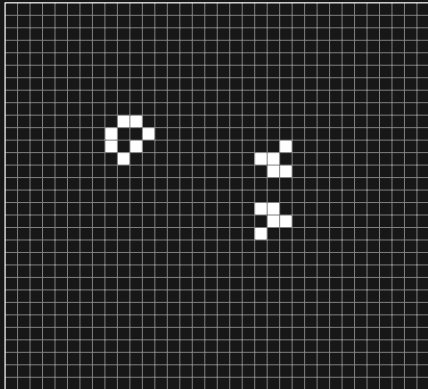
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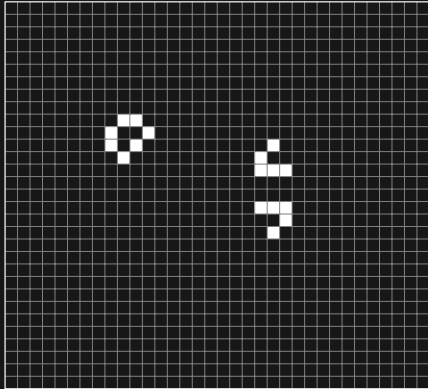
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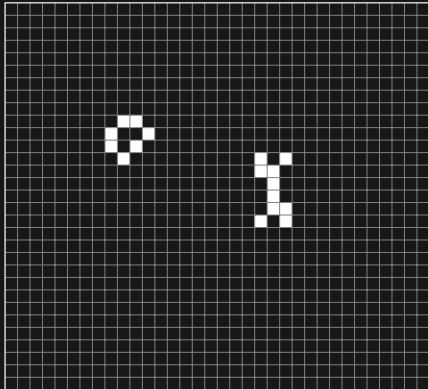
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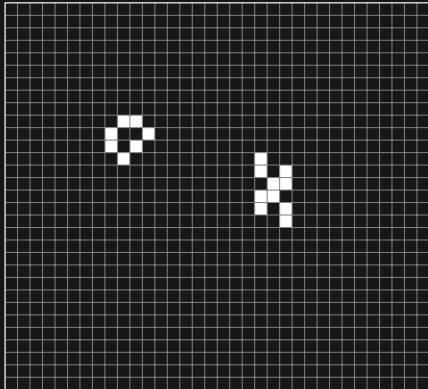
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Asynchronous Cellular Automata

An **Asynchronous Cellular Automaton** is a function $F : Q^{\mathbb{Z}^d} \rightarrow Q^{\mathbb{Z}^d}$:

$$F^{\sigma(0)}(x) = x; \quad F^{\sigma(t)}(x)_z = \begin{cases} f(F^{\sigma(t-1)}(x)_{N(z)}) & \text{if } z = \sigma(t) \\ x_z & \text{otherwise.} \end{cases}$$

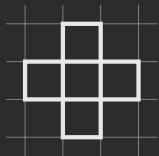
- ▶ $N \subset \mathbb{Z}^d$ is called the **neighborhood**
- ▶ f is the **local function**
- ▶ $\sigma : \mathbb{N} \rightarrow \mathbb{Z}^d$ is the **update scheme**

Remark

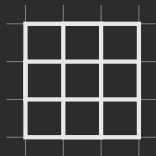
In **asynchronous** cellular automata only changes one cell at each time step.

Neighborhoods and Boolean Network

Main neighborhoods

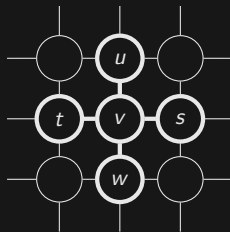
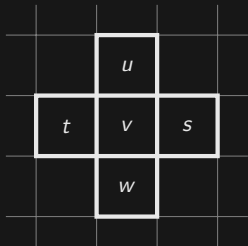


von Neumann
neighborhood



Moore
neighborhood

Neighborhoods and Boolean Network

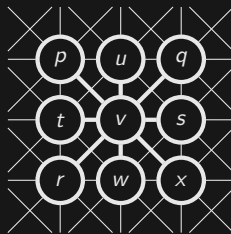


von Neumann Cellular automata grid Boolean network interaction graph

Neighborhoods and Boolean Network



Moore Cellular automata grid



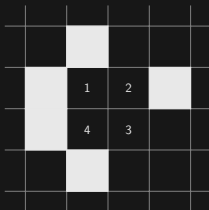
Boolean network interaction graph

Example: Life without Death.

Local function of Life without death

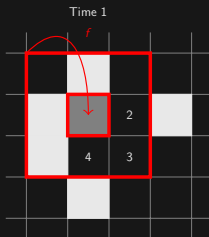


Time 1



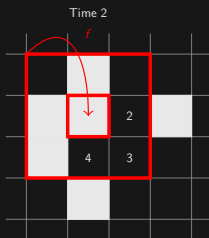
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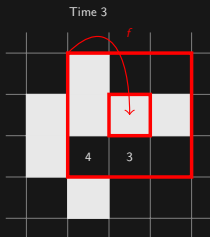
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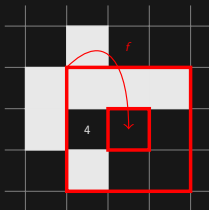


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Time 4

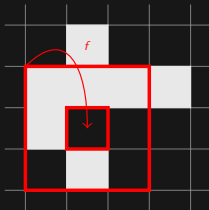


Example: Life without Death.

Local function of Life without death



Time 5

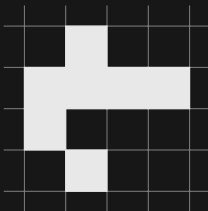


Example: Life without Death.

Local function of Life without death



Time 5



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Definition (AsyncUnstability_F)

F is a FACA.

INPUT: A $n \times n$ -periodic configuration x and a cell z .

QUESTION: Does there exist a updating scheme σ and $T > 0$ such that $F^{\sigma(T)}(x)_z \neq x_z$?

History

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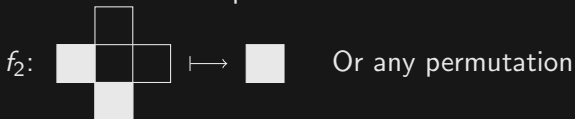
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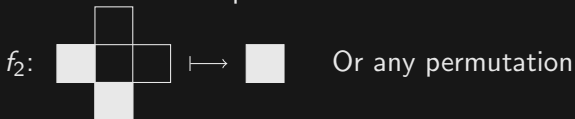
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A decision problem A is **NP-Complete** if A is in NP and for each problem B in P B can be reduced to A , i.e. there is a ϕ polynomial s.t. $\forall x, B(x) = \text{true} \Leftrightarrow A(\phi(x)) = \text{true}$

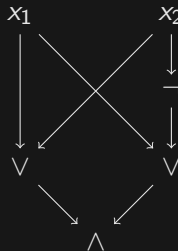
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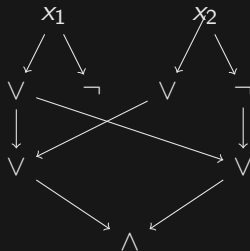
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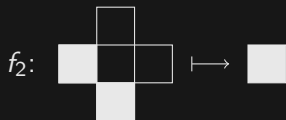
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We will study the following FACA with von Neumann neighborhood:

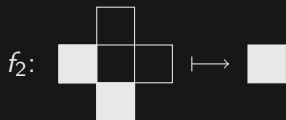


Or any permutation

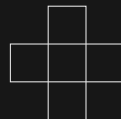


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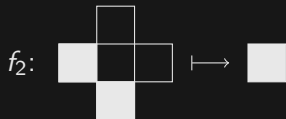


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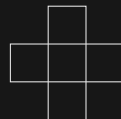
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Is AsyncUnstability NP-complete for f_2 ?

Previous Works

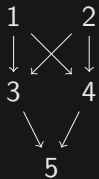
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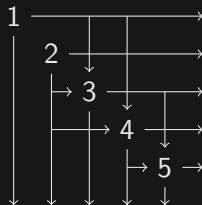
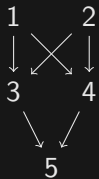
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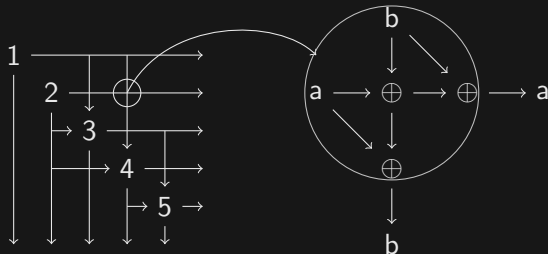
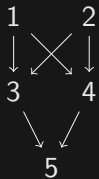
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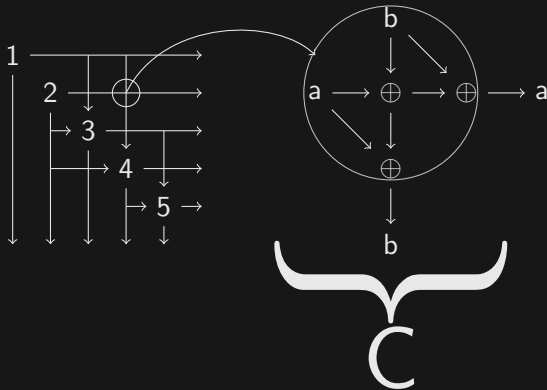
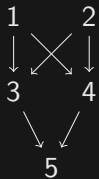
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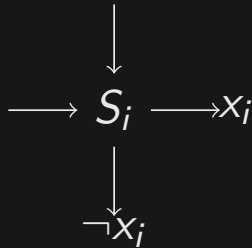
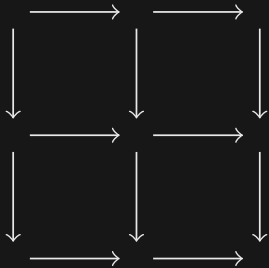


Lemma 1

South-East grid-embedded circuit SAT is NP-complete, with gates $\wedge, \vee, 0, C$ and S_i , where S_i sends a value for the South output and the opposite value for the East output and C is a crossing gate.

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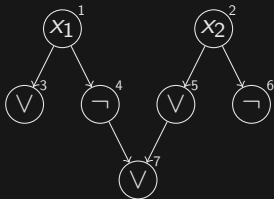
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$$\phi(x_1, x_2) = \neg x_1 \vee x_2$$

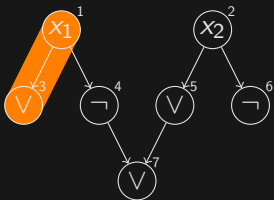


	1	2	3	4	5	6	7
1	S_1	C	T	C	C	C	C
2	C	S_2	C	C	T	C	C
3	C	C	\vee	C	C	C	C
4	\neg	C	C	\vee	C	C	C
5	C	C	C	C	\vee	C	T
6	C	\neg	C	C	C	\vee	C
7	C	C	C	\neg	C	C	\vee

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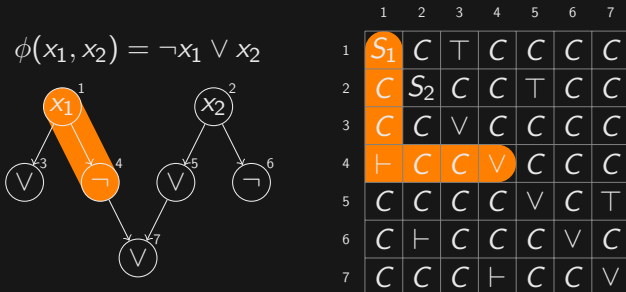
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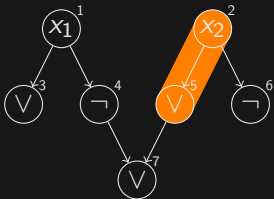
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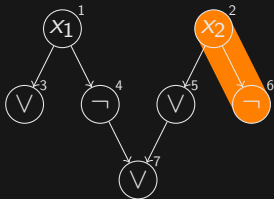


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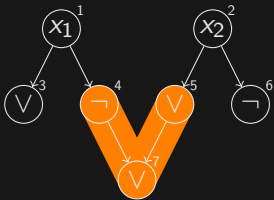


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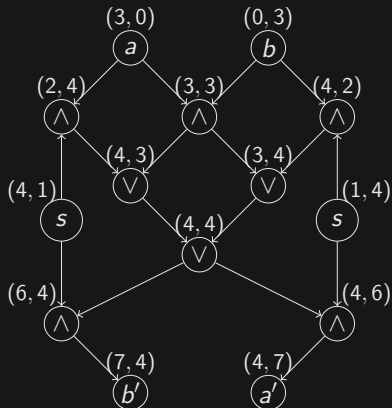
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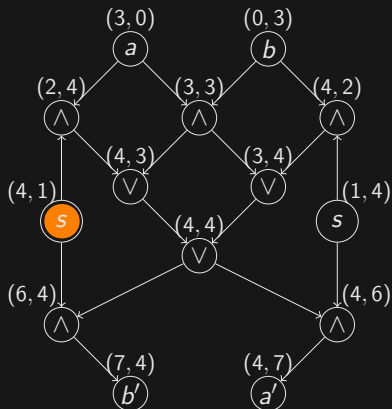
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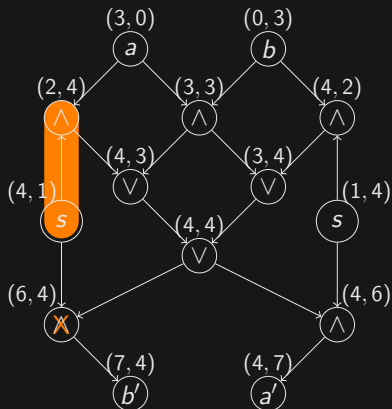
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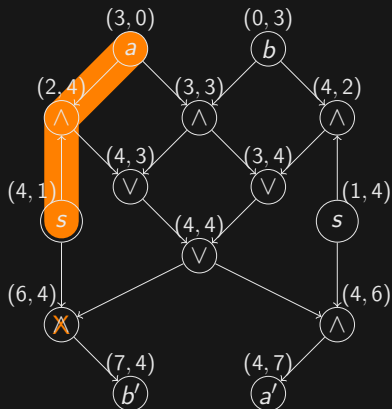
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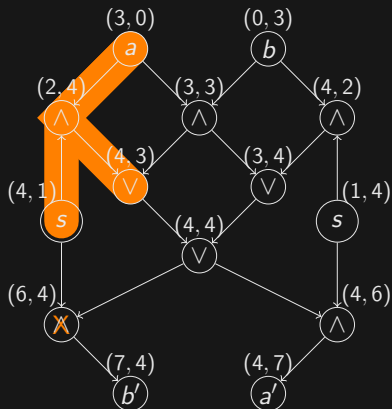
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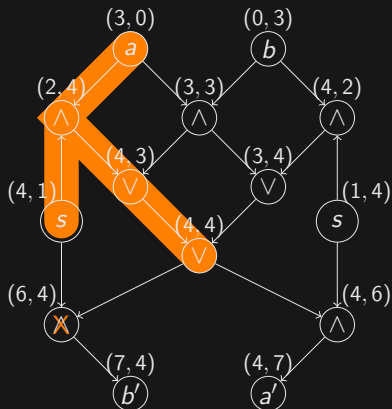
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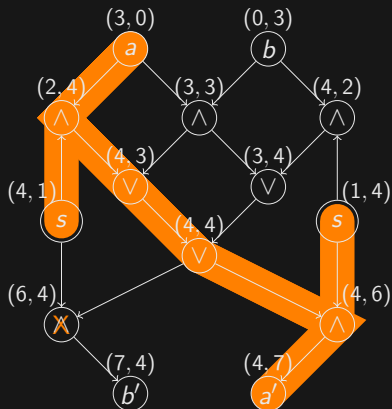
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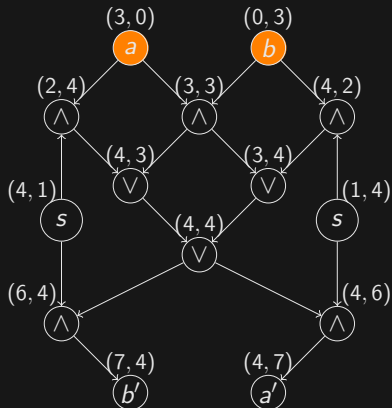
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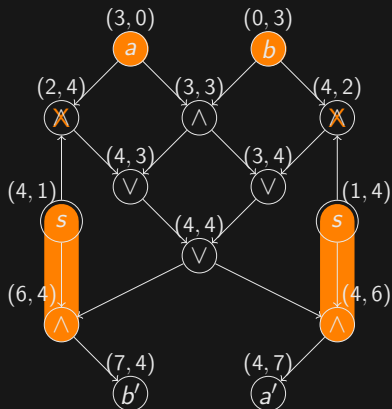
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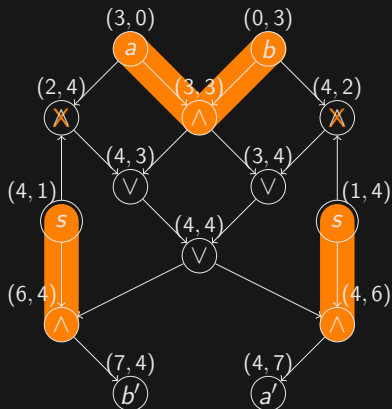
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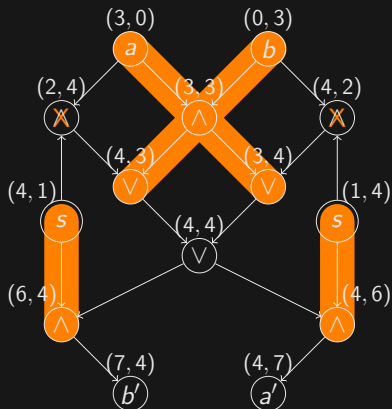
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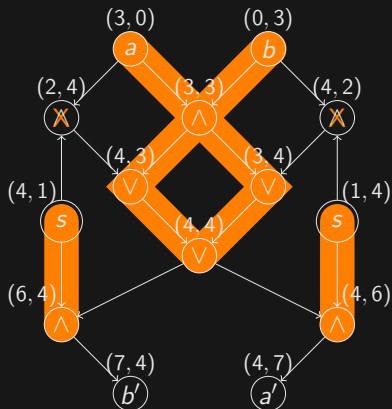
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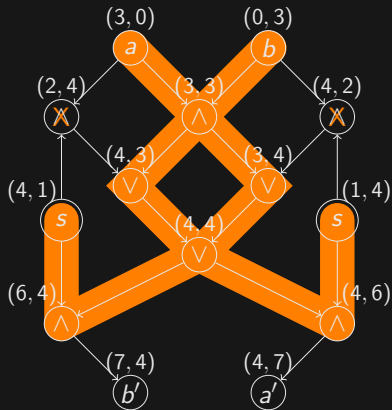
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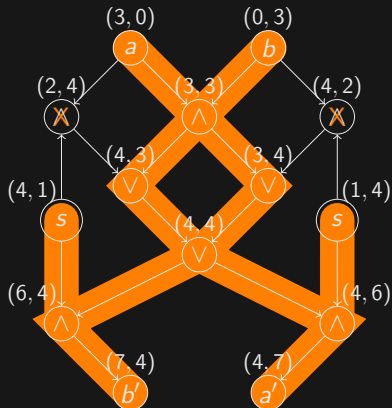
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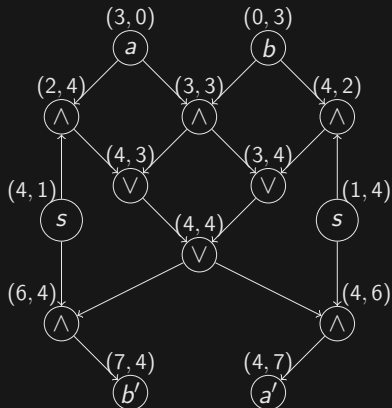
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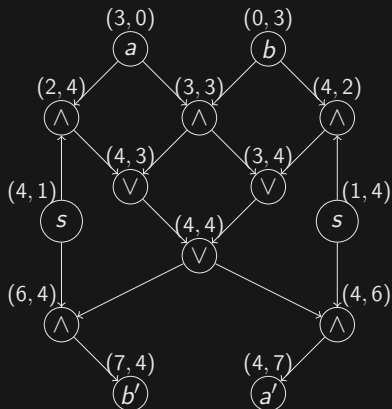
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a	b	s_1	s_2	a'	b'
0	0	↓	↓	0	0
0	0	↓	→	0	0
0	0	→	↓	0	0
0	0	→	→	0	0
0	1	↓	↓	0	1
0	1	↓	→	0	0
0	1	→	↓	0	0
0	1	→	→	0	0
1	0	↓	↓	0	0
1	0	↓	→	0	0
1	0	→	↓	0	0
1	0	→	→	1	0
1	1	↓	↓	0	1
1	1	↓	→	1	1
1	1	→	↓	0	0
1	1	→	→	1	0

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	0	1	2	3	4	5	6	7
0	0	0	0	\vee	0	0	0	0
1	0	0	0	\vee	S	\vee	\vee	0
2	0	0	0	\vee	\wedge	0	\vee	0
3	\vee	\vee	\vee	\wedge	\vee	0	\vee	0
4	0	S	\wedge	\vee	\vee	\vee	\wedge	\vee
5	0	\vee	0	0	\vee	0	0	0
6	0	\vee	\vee	\vee	\wedge	0	0	0
7	0	0	0	0	\vee	0	0	0

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0	0	0	0	\vee	0	0	0	0
1	0	0	0	\vee	S	\vee	\vee	0
2	0	0	0	\vee	\wedge	0	\vee	0
3	\vee	\vee	\vee	\wedge	\vee	0	\vee	0
4	0	S	\wedge	\vee	\vee	\vee	\wedge	\vee
5	0	\vee	0	0	\vee	0	0	0
6	0	\vee	\vee	\vee	\wedge	0	0	0
7	0	0	0	0	\vee	0	0	0

Problem!!!

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	0	1	2	3	4	5	6	7
0	0	0	0	\vee	0	0	0	0
1	0	0	0	\vee	S	\vee	\vee	0
2	0	0	0	\vee	\wedge	0	\vee	0
3	\vee	\vee	\vee	\wedge	\vee	0	\vee	0
4	0	S	\wedge	\vee	\vee	\vee	\wedge	\vee
5	0	\vee	0	0	\vee	0	0	0
6	0	\vee	\vee	\vee	\wedge	0	0	0
7	0	0	0	0	\vee	0	0	0

	0	1	2	3	4	5	6	7
0	0	0	0	\vee	0	0	0	0
1	0	0	0	\vee	S	\vee	\vee	0
2	0	0	0	\vee	\wedge	0	\vee	0
3	\vee	\vee	\vee	\wedge	\vee	0	\vee	0
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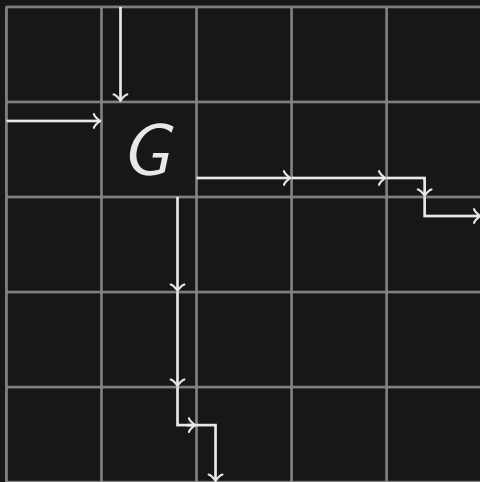
Gates \vee , \wedge , 0 and S

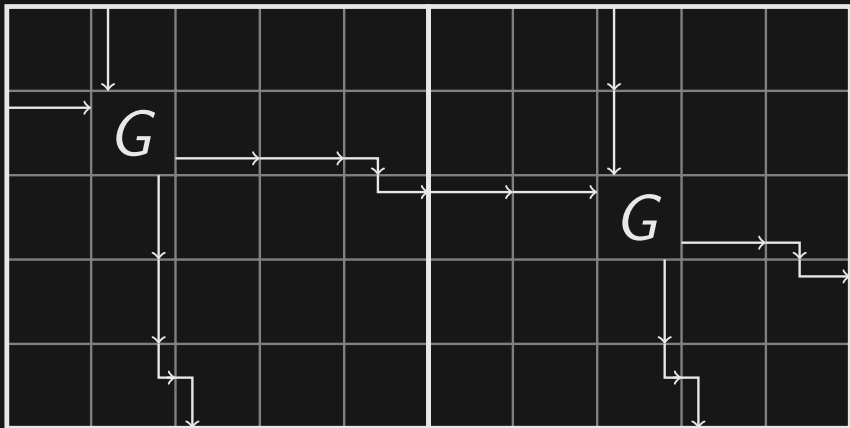
0	0	0	\vee	0	0	0	0
0	0	0	\vee	0	0	0	0
0	0	0	\vee	0	0	0	0
\vee	\vee	\vee	\vee	\vee	0	0	0
0	0	0	0	\vee	\vee	\vee	\vee
0	0	0	0	\vee	0	0	0
0	0	0	0	\vee	0	0	0
0	0	0	0	\vee	0	0	0

0	0	0	\vee	0	0	0	0
0	0	0	\vee	0	0	0	0
0	0	0	\vee	0	0	0	0
\vee	\vee	\vee	\wedge	\vee	0	0	0
0	0	0	0	\vee	\vee	\vee	\vee
0	0	0	0	\vee	0	0	0
0	0	0	0	\vee	0	0	0
0	0	0	0	\vee	0	0	0

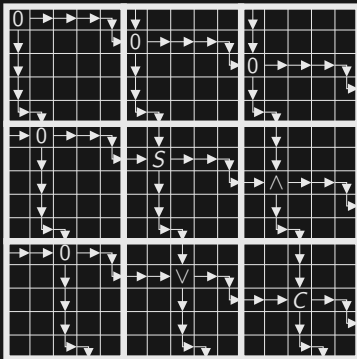
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	S	\vee	\vee	\vee
0	0	0	0	\vee	0	0	0
0	0	0	0	\vee	0	0	0
0	0	0	0	\vee	0	0	0

0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	\vee	\vee	\vee	\vee
0	0	0	0	\vee	0	0	0
0	0	0	0	\vee	0	0	0
0	0	0	0	\vee	0	0	0





0	0	0
0	S	\wedge
0	\vee	C



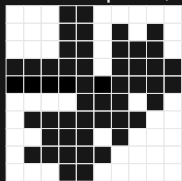
Therefore South-East grid-embedded circuit SAT is NP-complete,
with gates \wedge , \vee , 0 and S_i .

Finally...

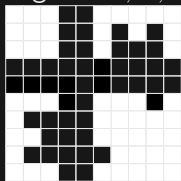
Theorem

AsyncUnstability is NP-complete.

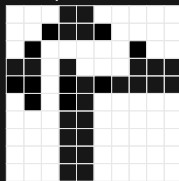
Remember: South-East grid-embedded circuit SAT is NP-complete, with gates \vee , \wedge , 0 and S_i .



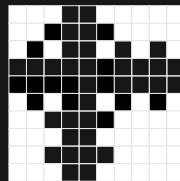
\vee



\wedge

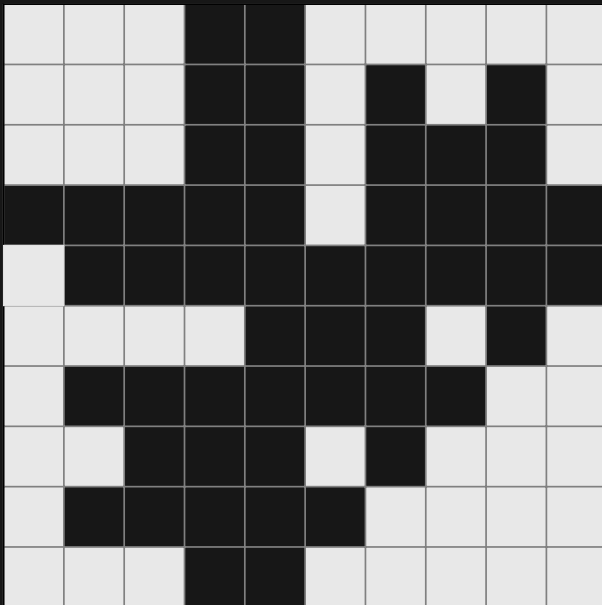


S

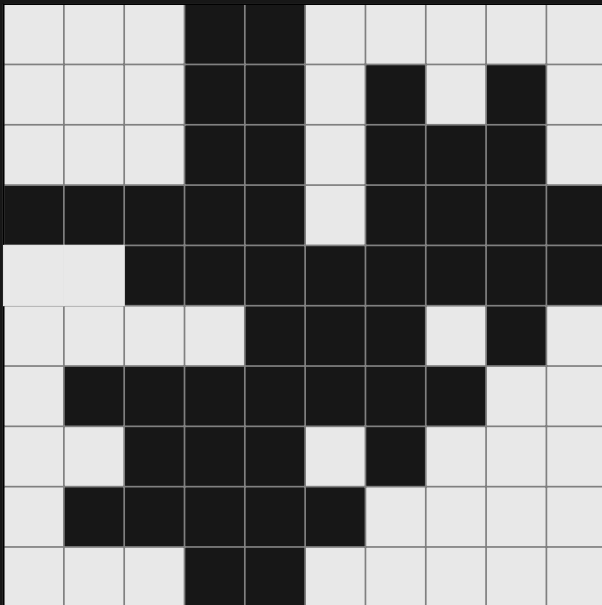


0

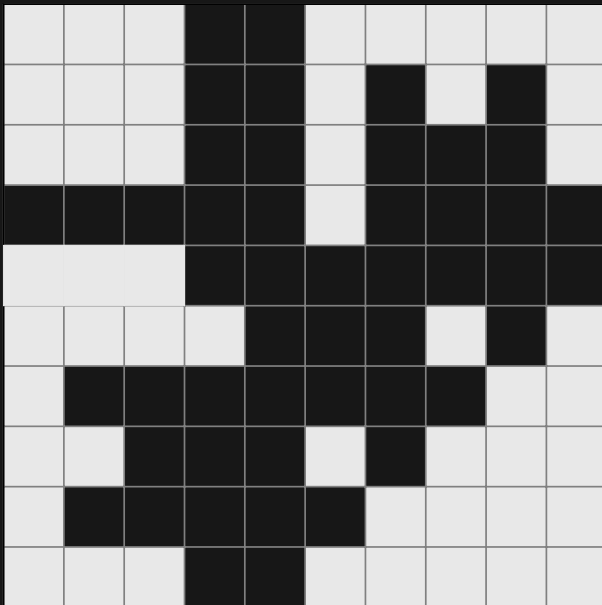
OR gate in f_2



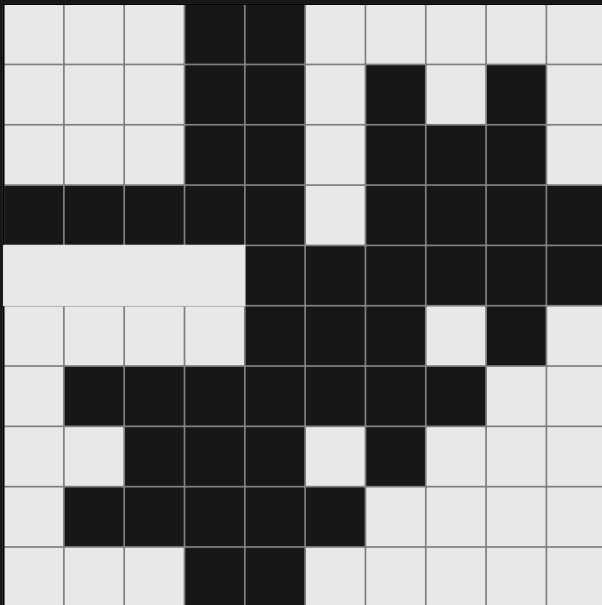
OR gate in f_2



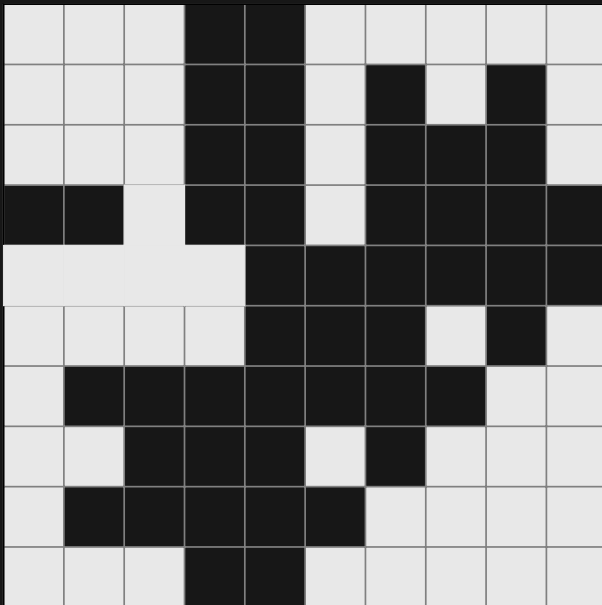
OR gate in f_2



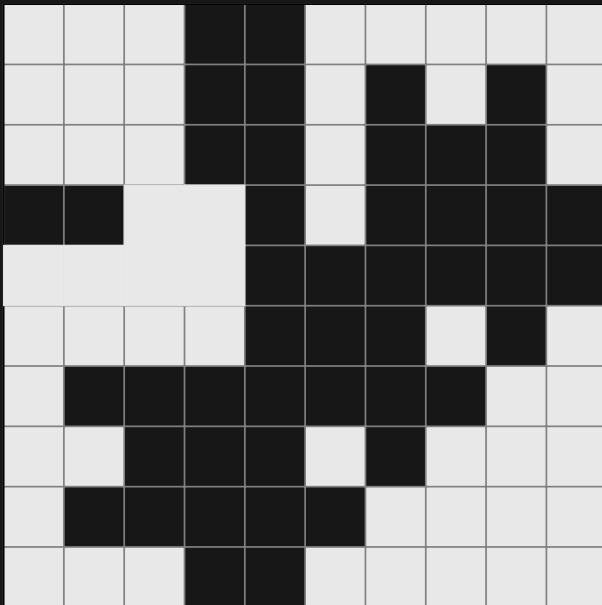
OR gate in f_2



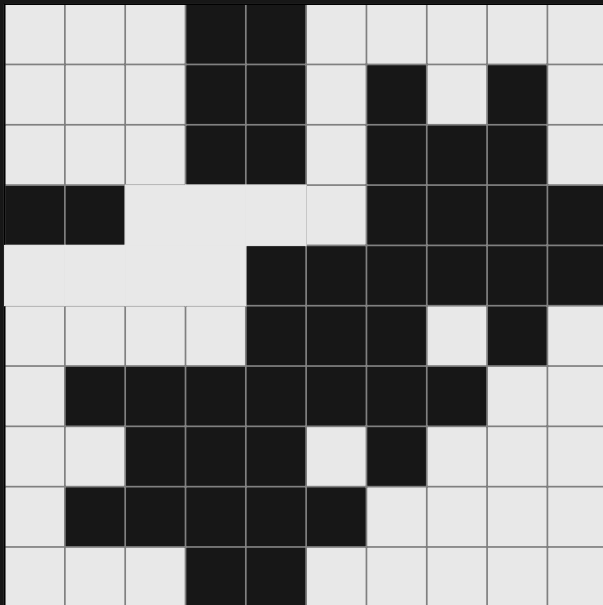
OR gate in f_2



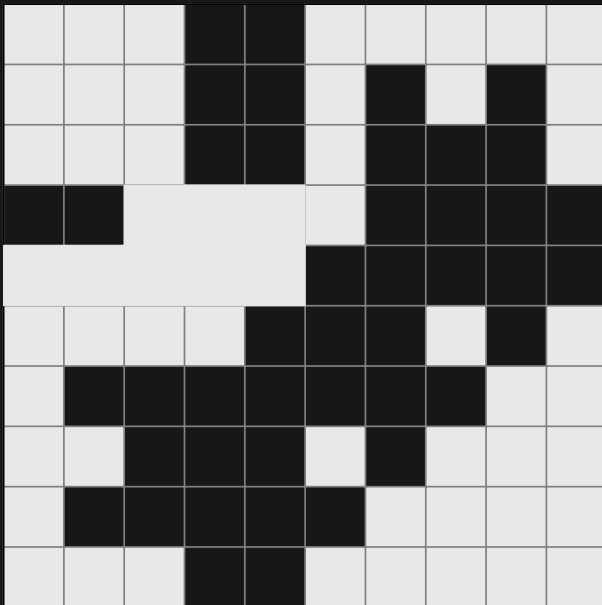
OR gate in f_2



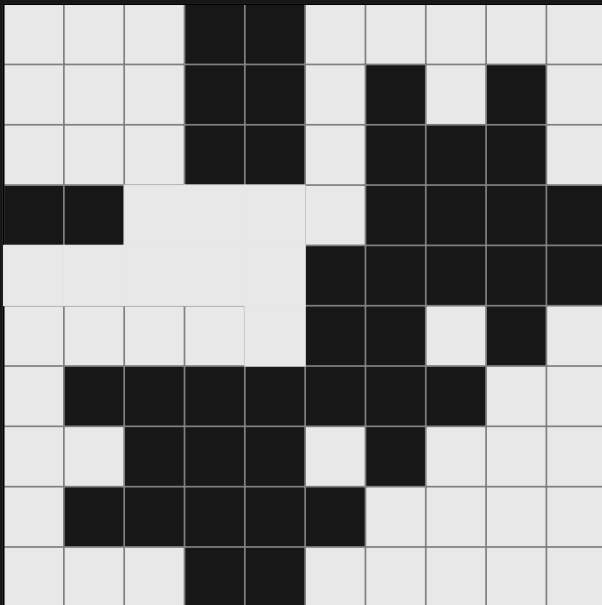
OR gate in f_2



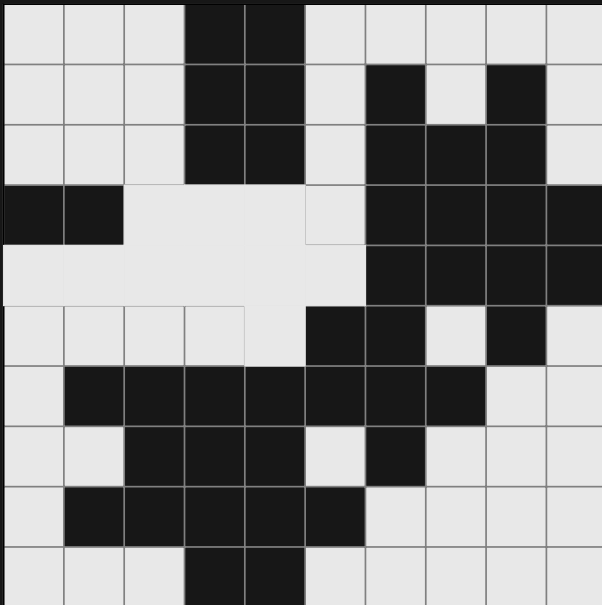
OR gate in f_2



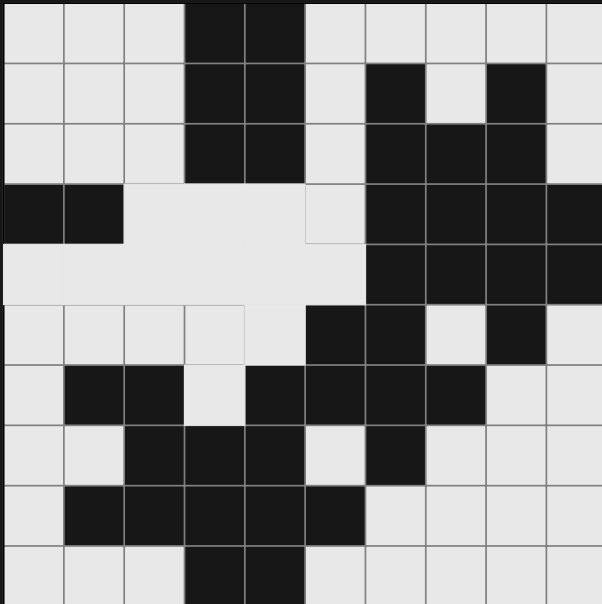
OR gate in f_2



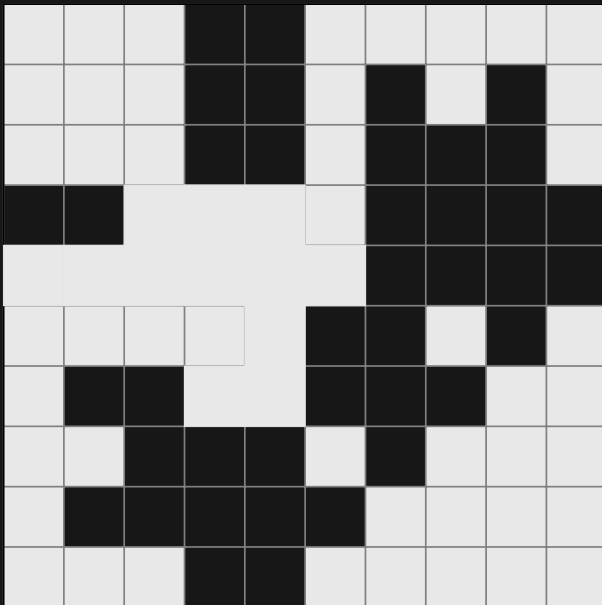
OR gate in f_2



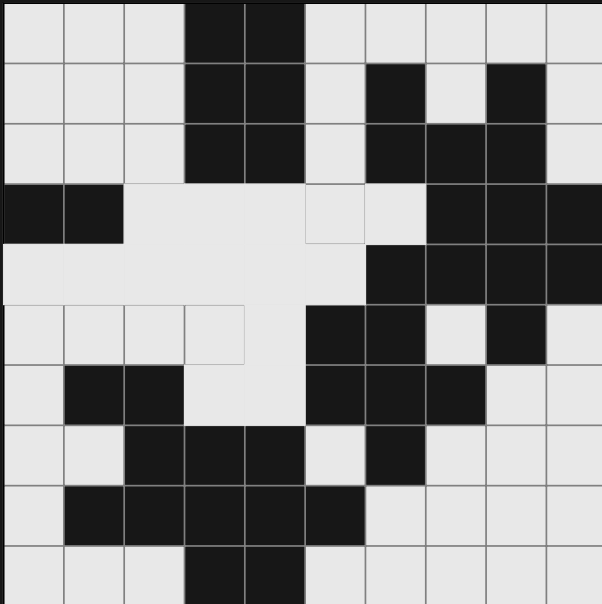
OR gate in f_2



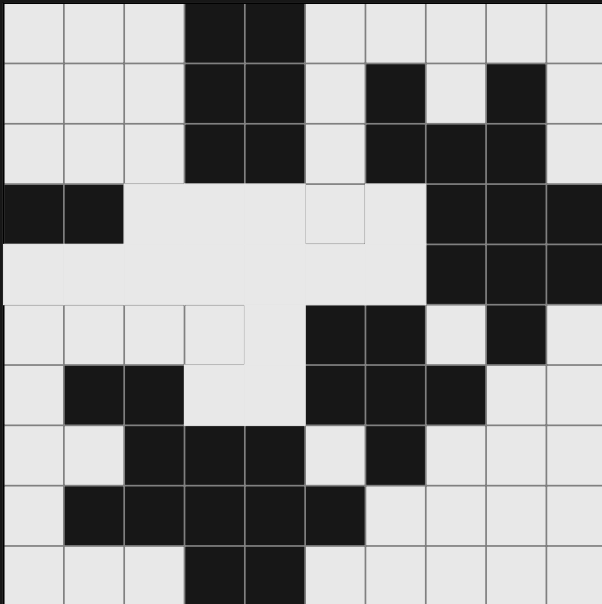
OR gate in f_2



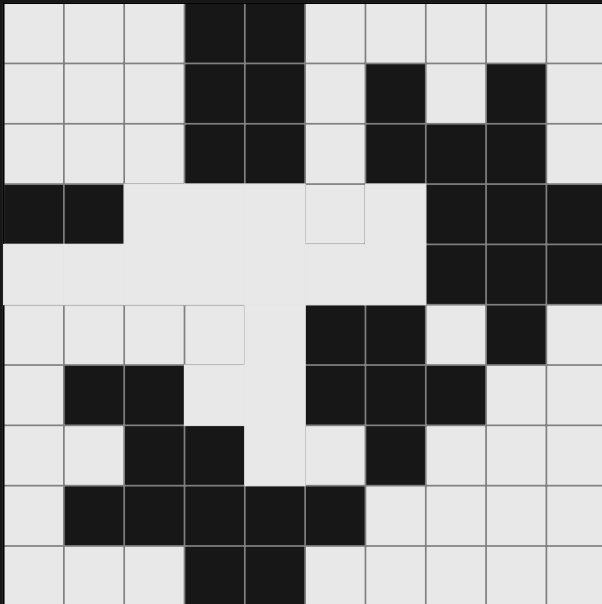
OR gate in f_2



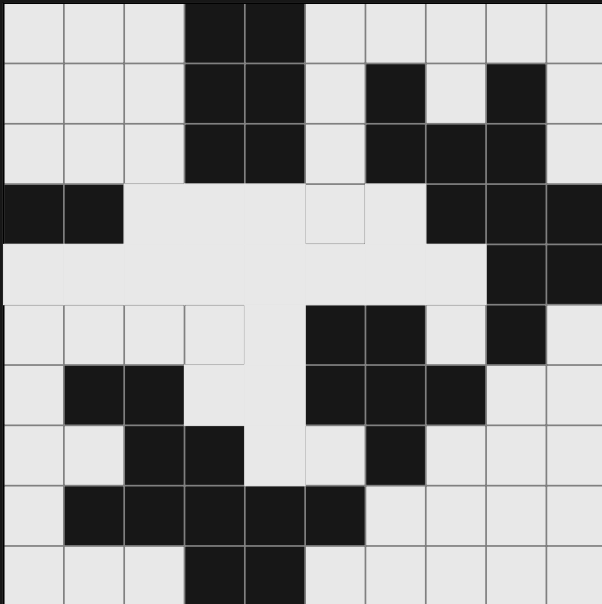
OR gate in f_2



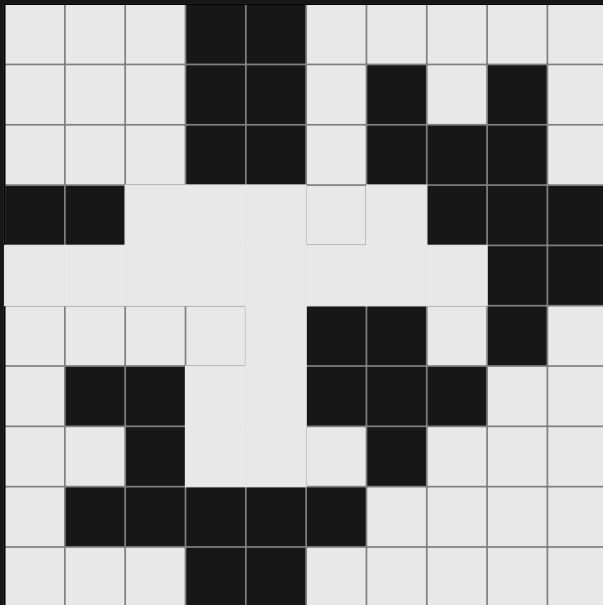
OR gate in f_2



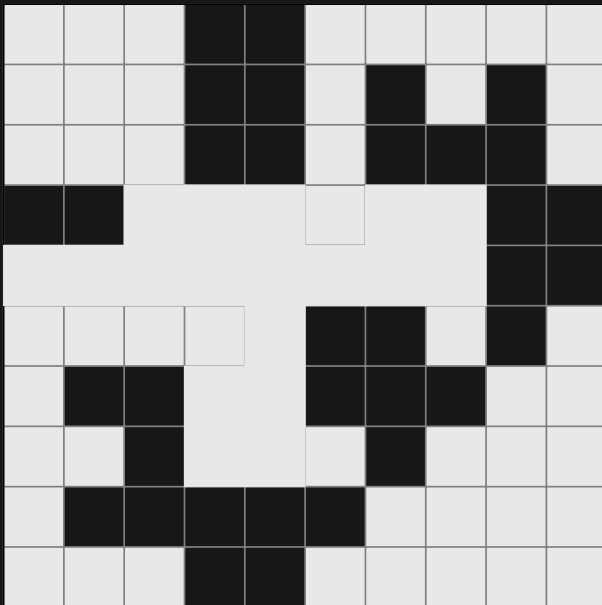
OR gate in f_2



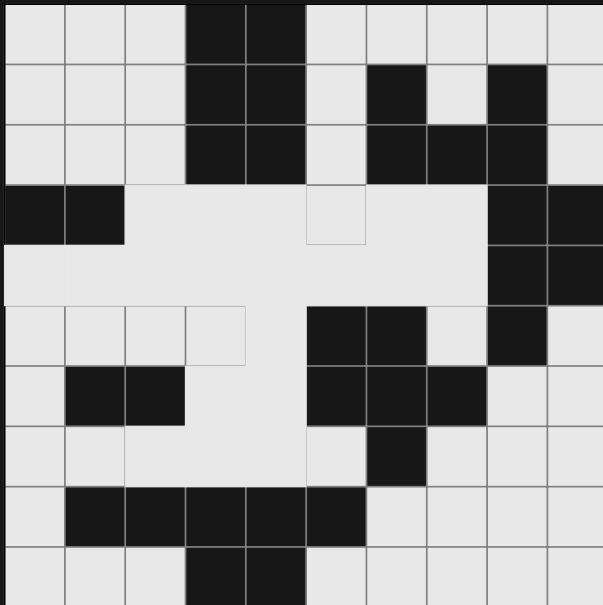
OR gate in f_2



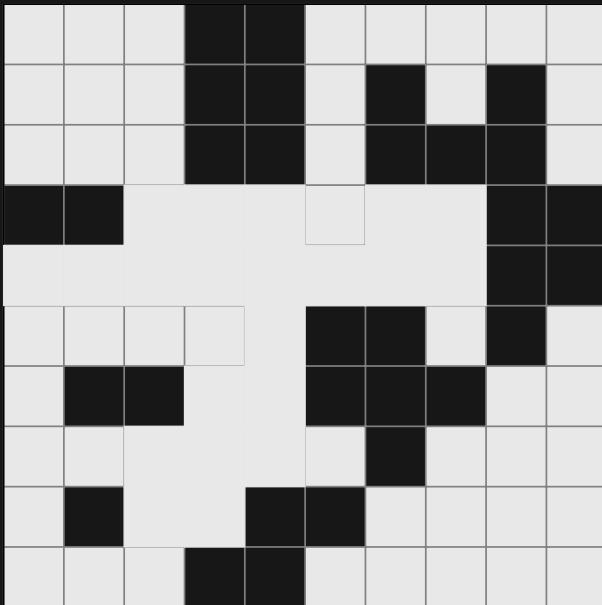
OR gate in f_2



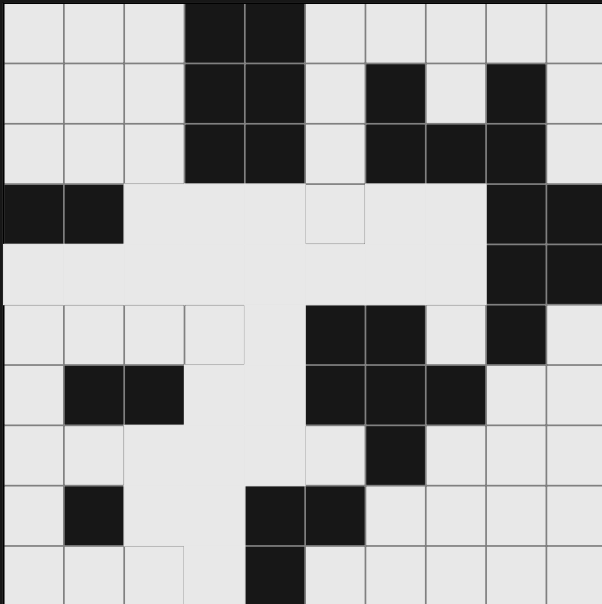
OR gate in f_2



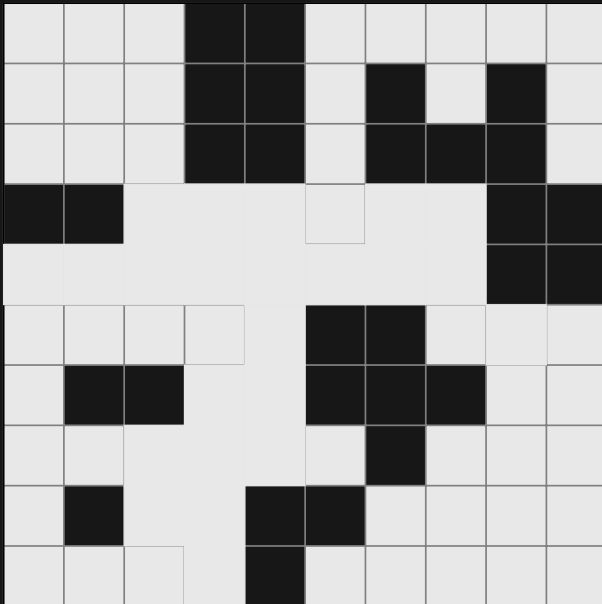
OR gate in f_2



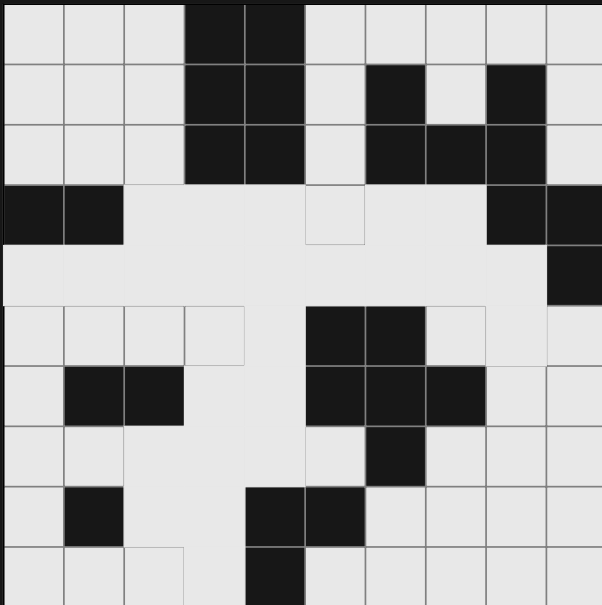
OR gate in f_2



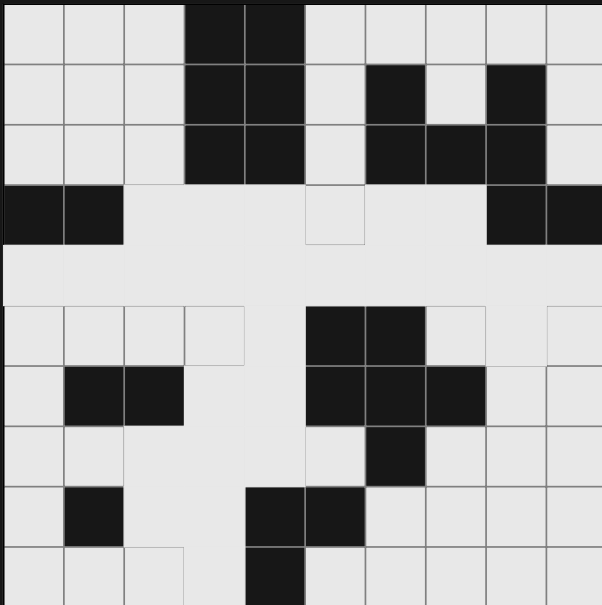
OR gate in f_2



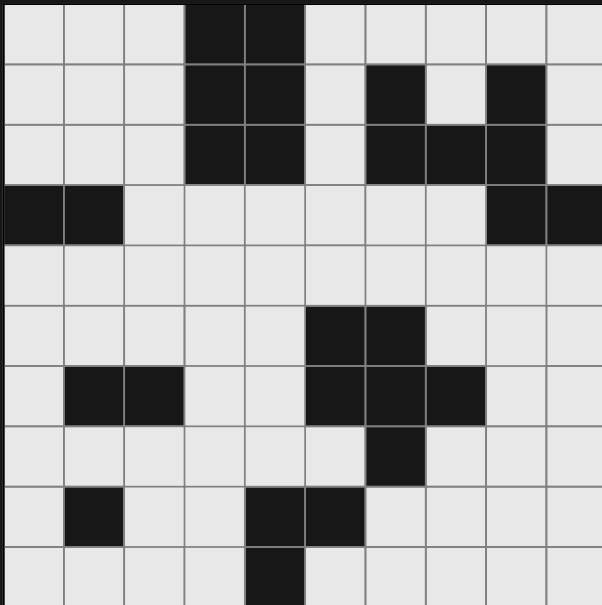
OR gate in f_2



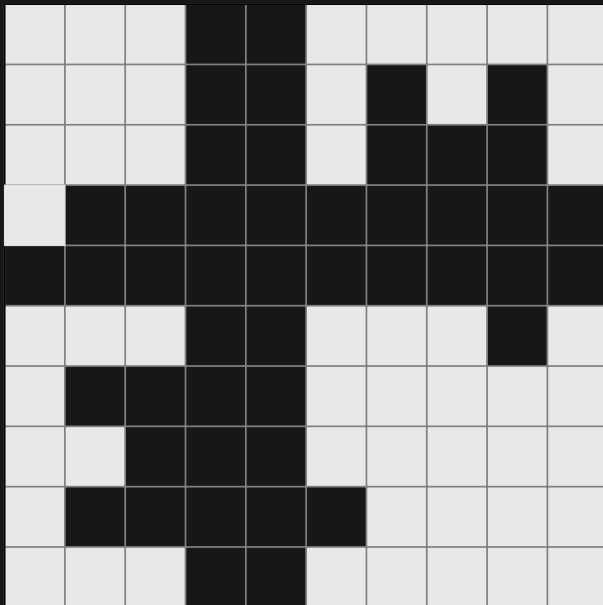
OR gate in f_2



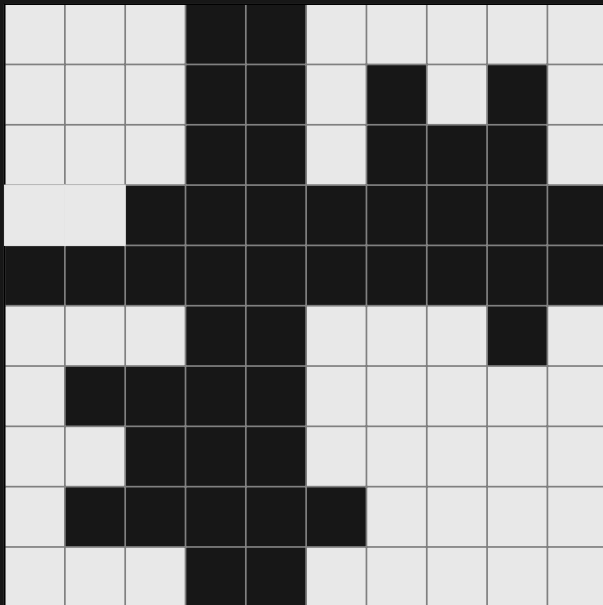
OR gate in f_2



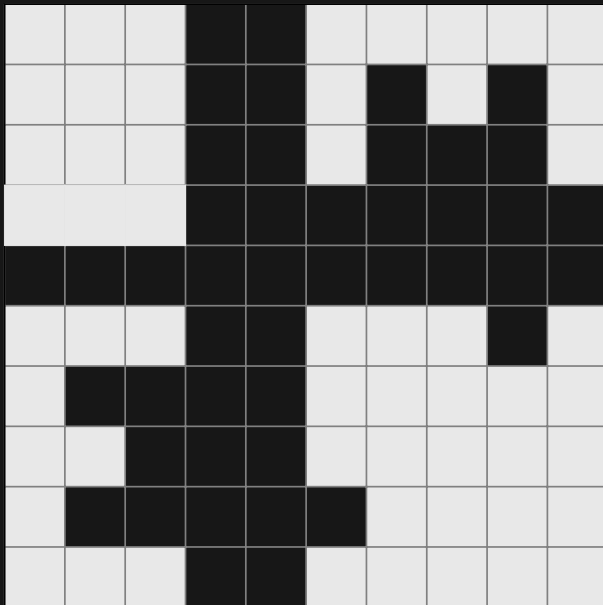
AND gate in f_2



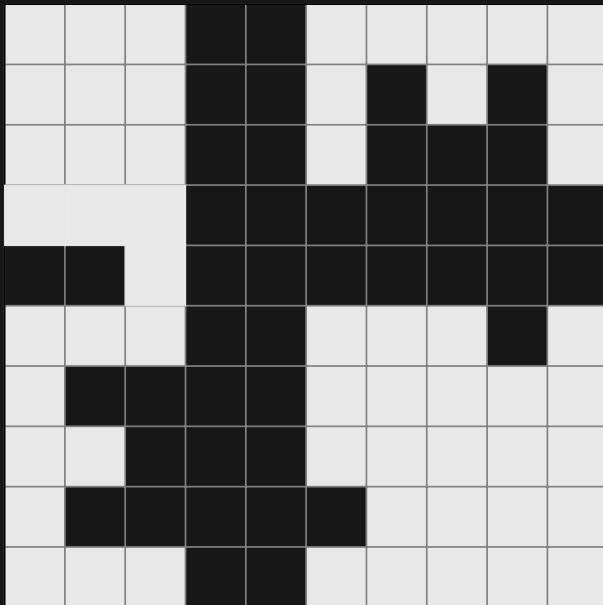
AND gate in f_2



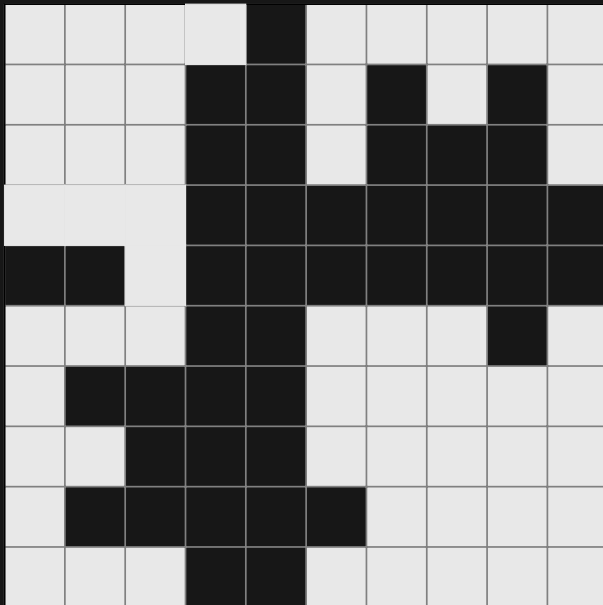
AND gate in f_2



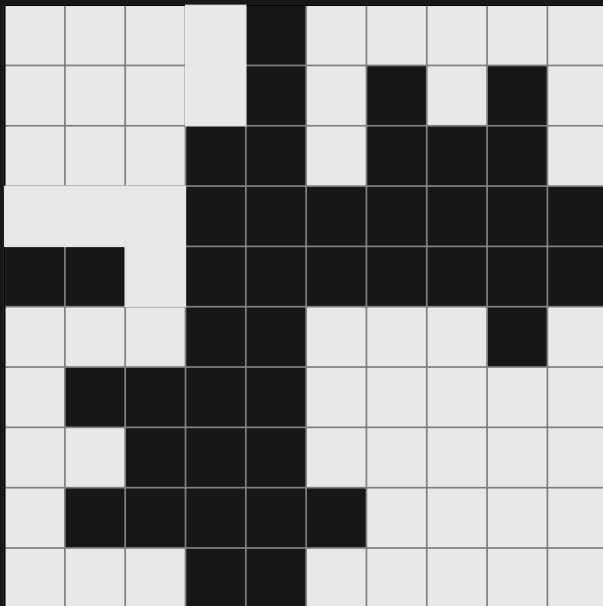
AND gate in f_2



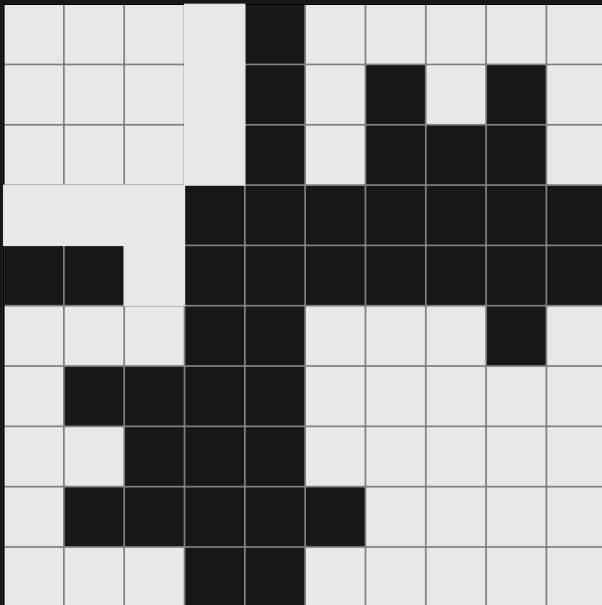
AND gate in f_2



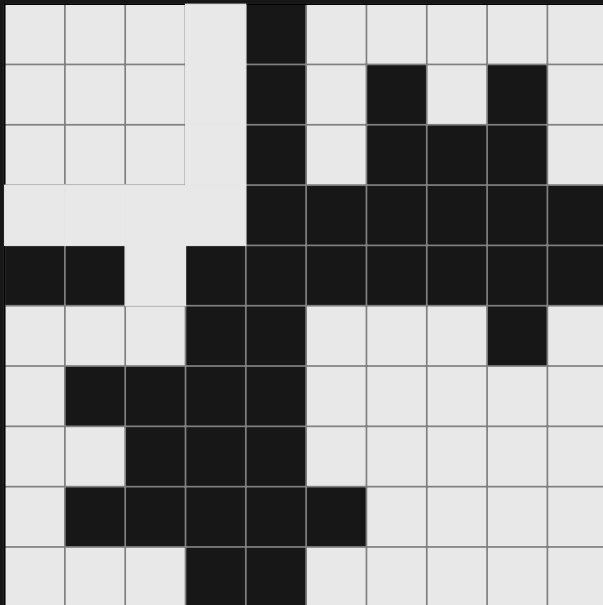
AND gate in f_2



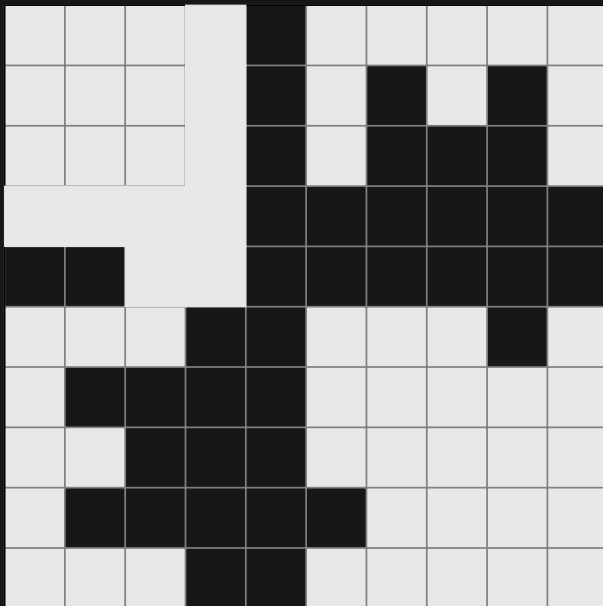
AND gate in f_2



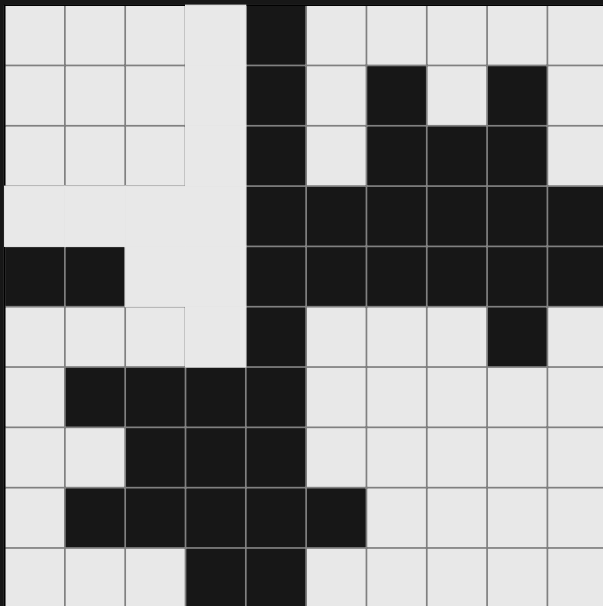
AND gate in f_2



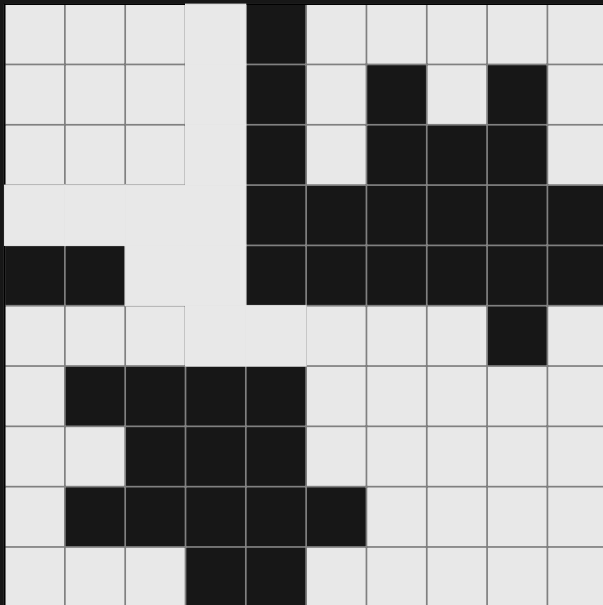
AND gate in f_2



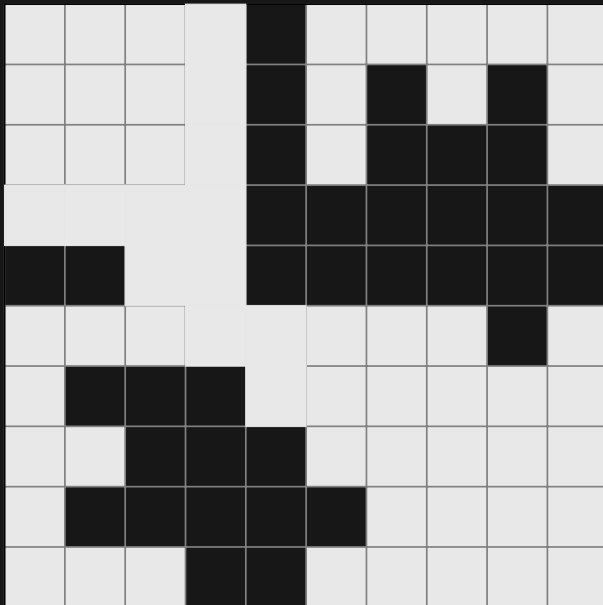
AND gate in f_2



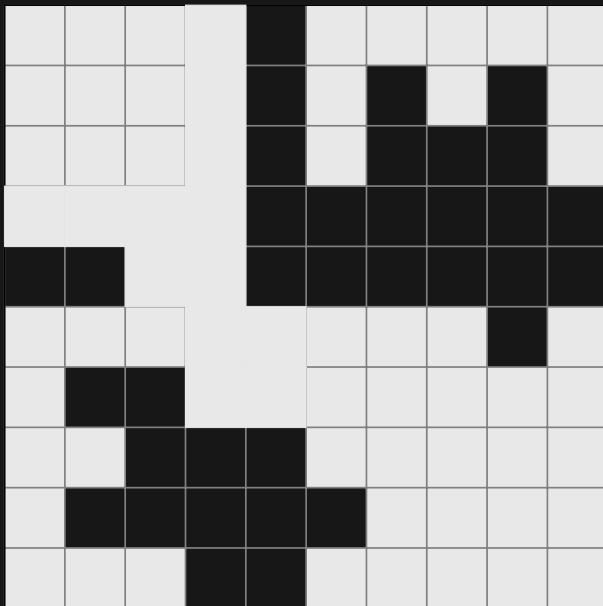
AND gate in f_2



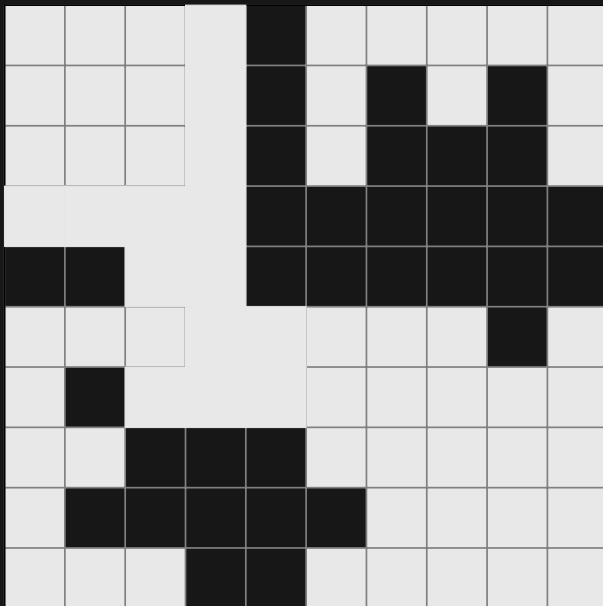
AND gate in f_2



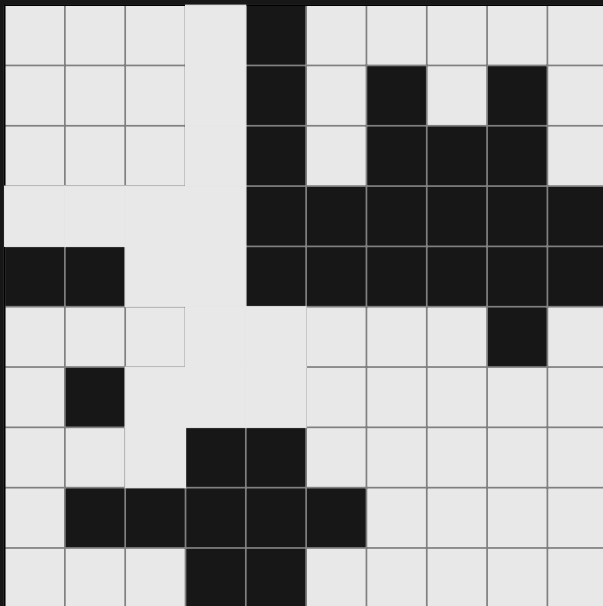
AND gate in f_2



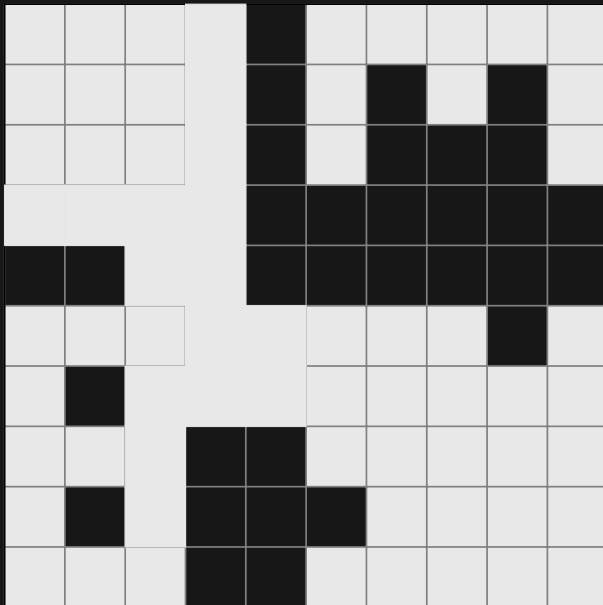
AND gate in f_2



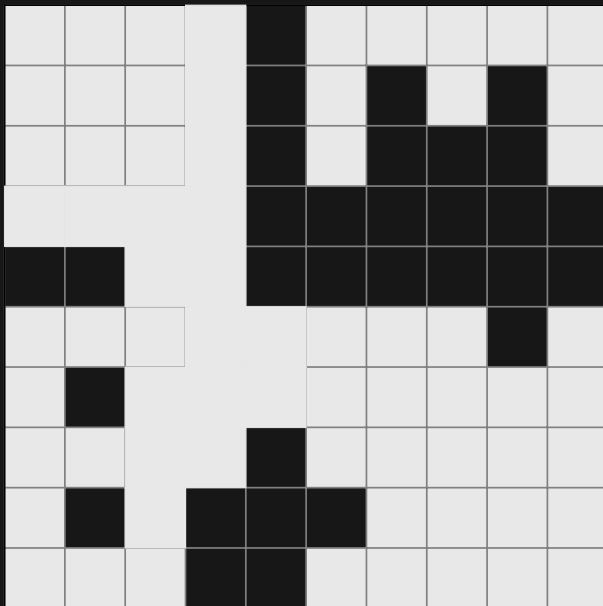
AND gate in f_2



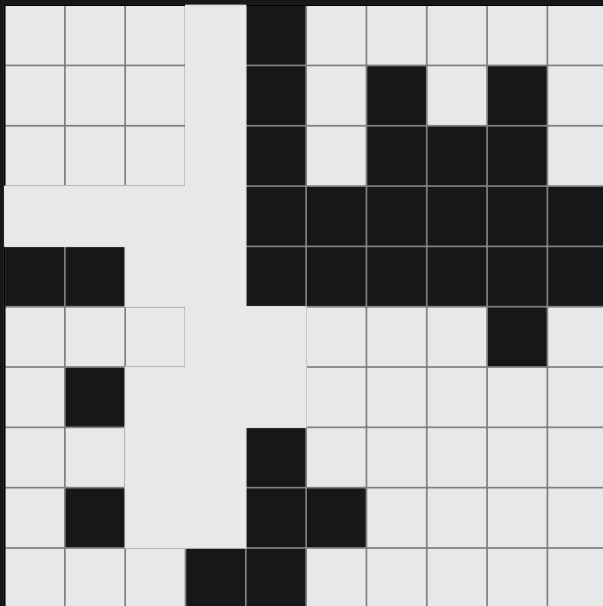
AND gate in f_2



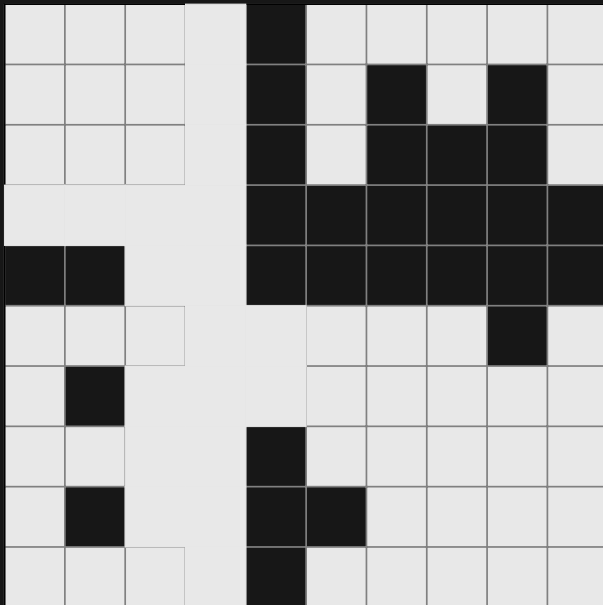
AND gate in f_2



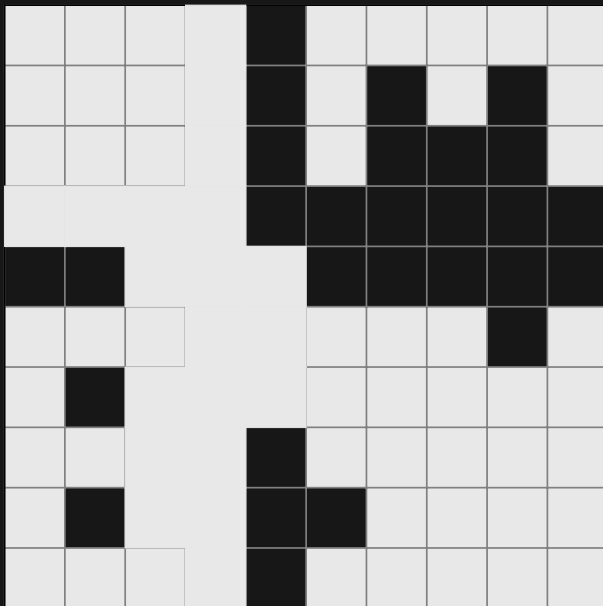
AND gate in f_2



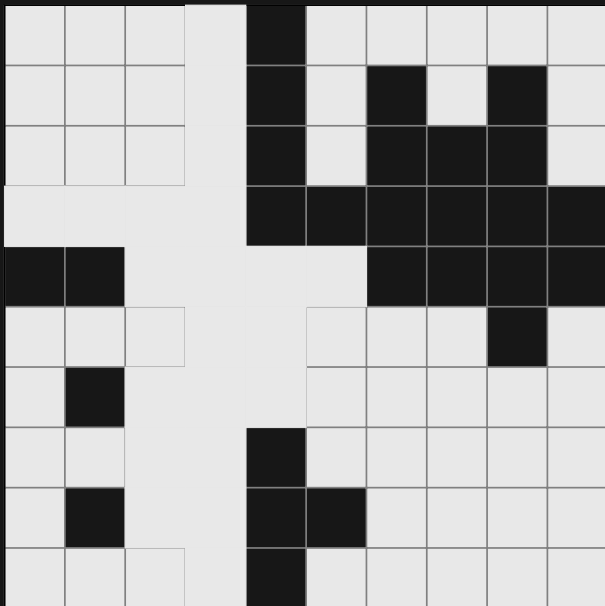
AND gate in f_2



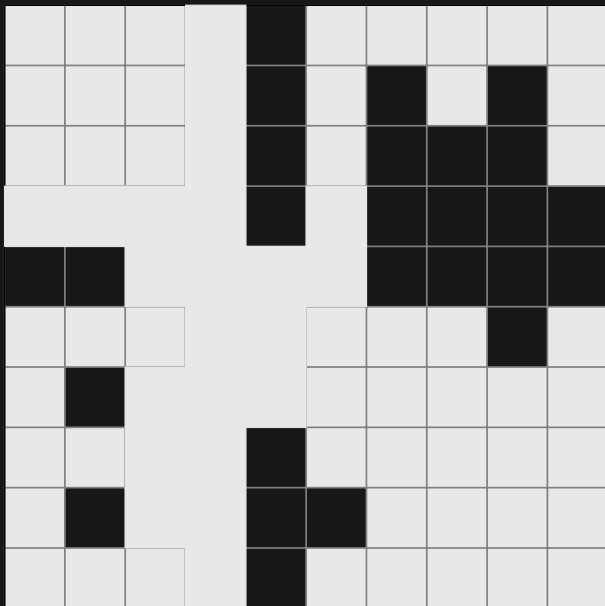
AND gate in f_2



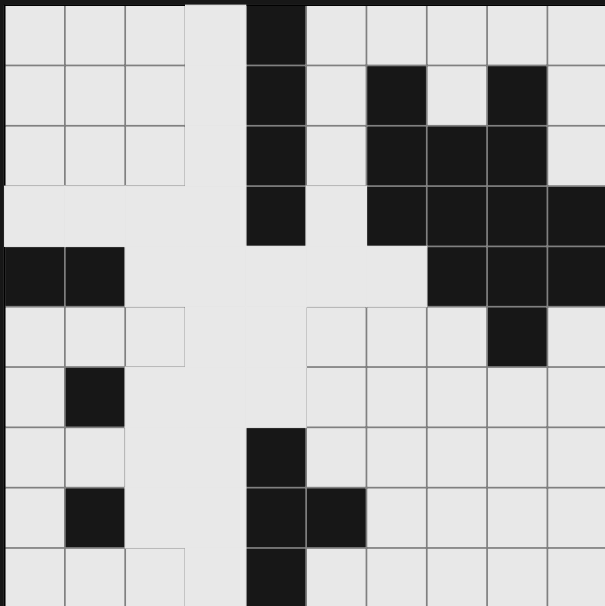
AND gate in f_2



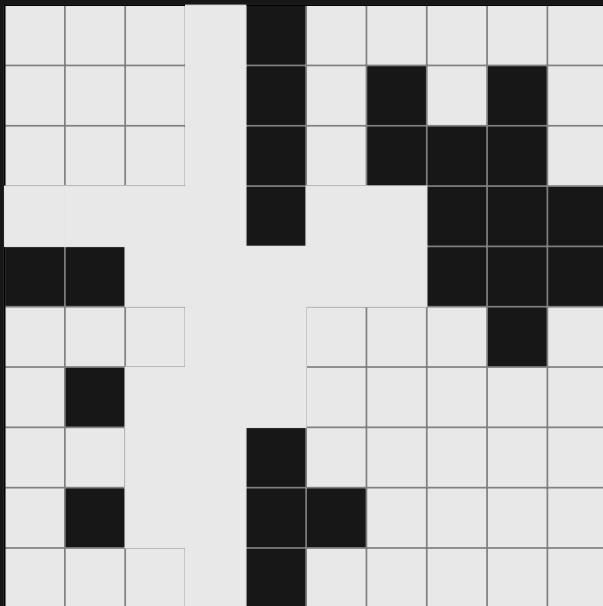
AND gate in f_2



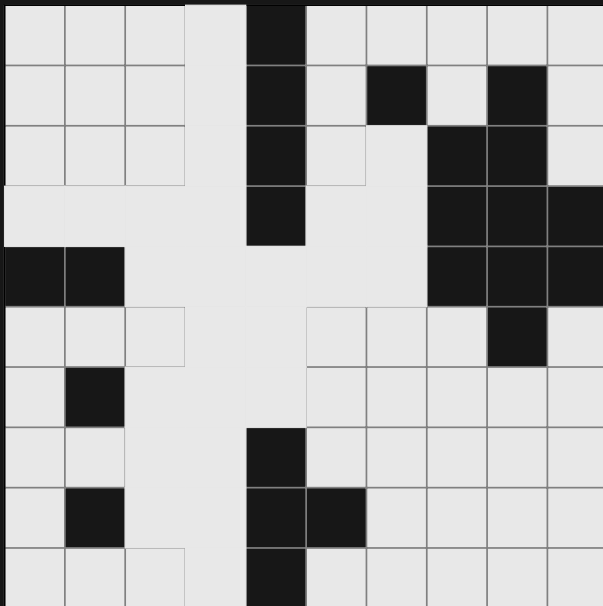
AND gate in f_2



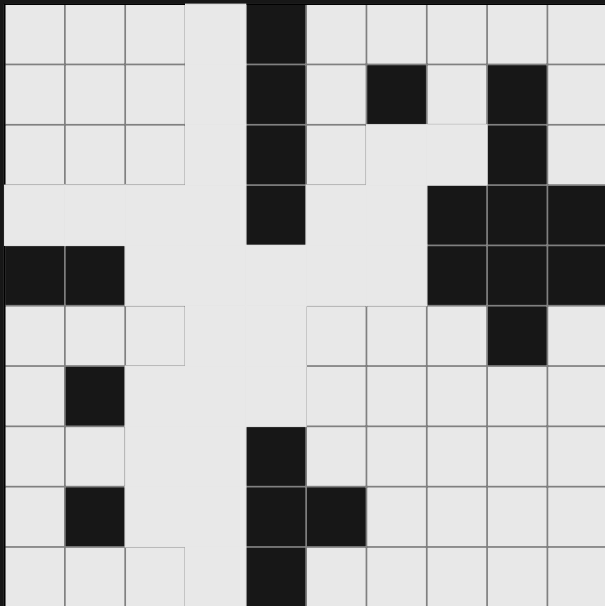
AND gate in f_2



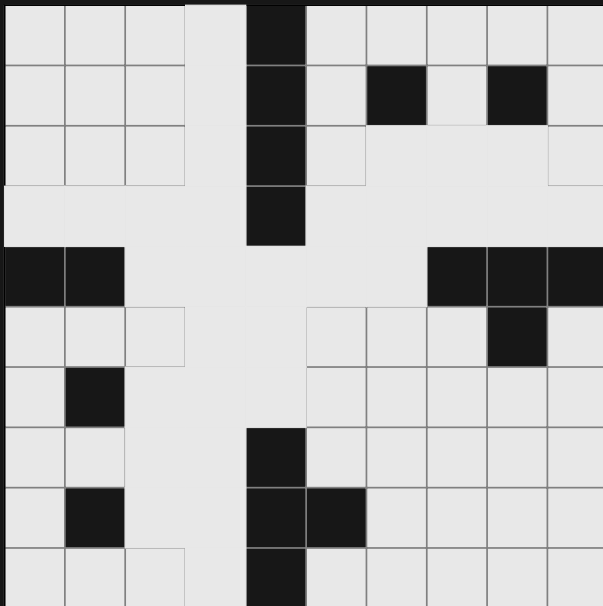
AND gate in f_2



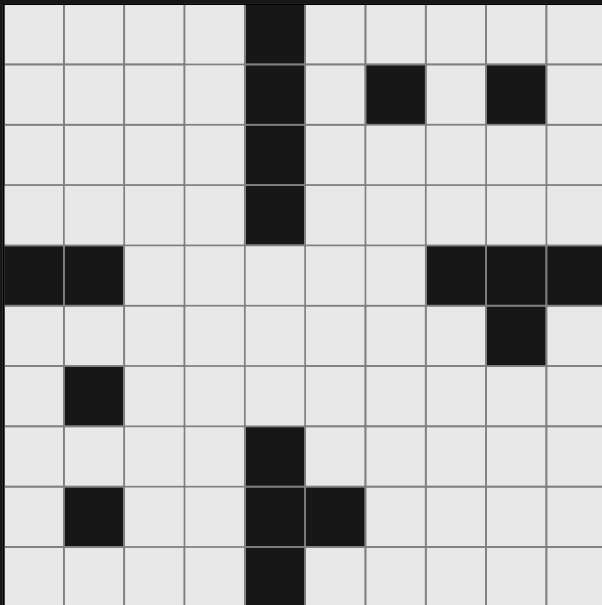
AND gate in f_2



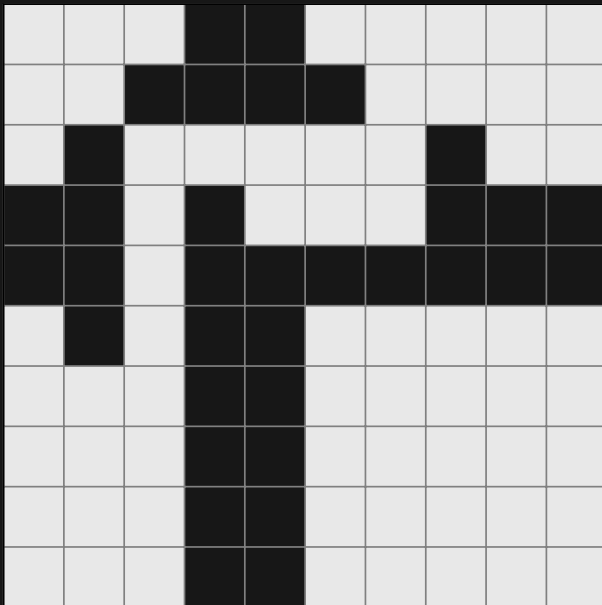
AND gate in f_2



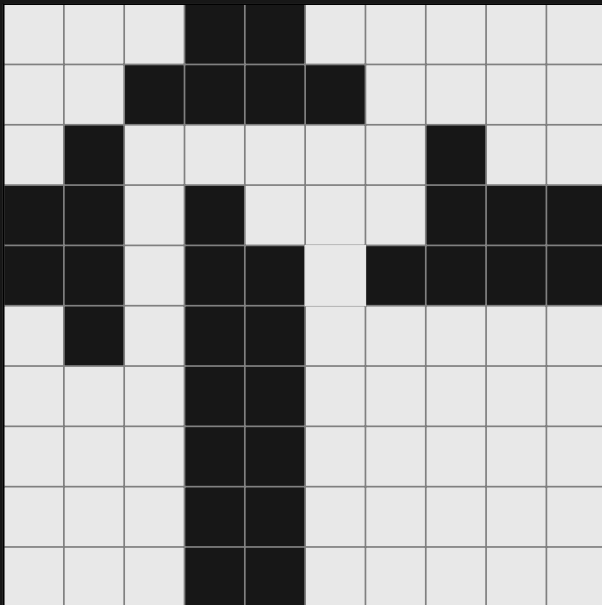
AND gate in f_2



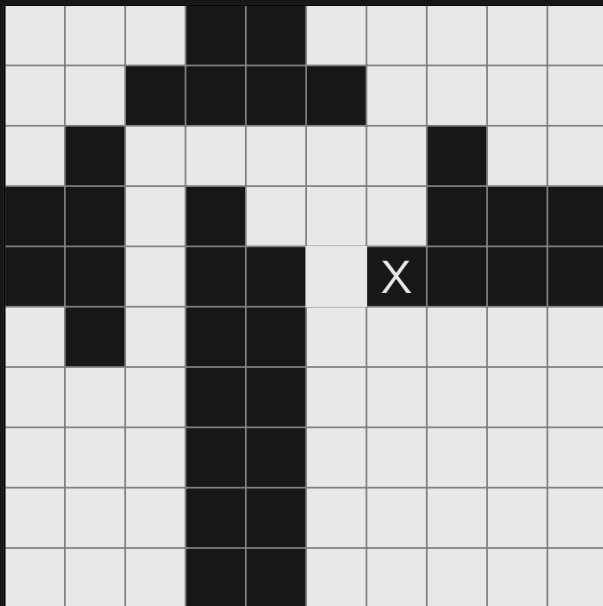
S_i gate in f_2 I



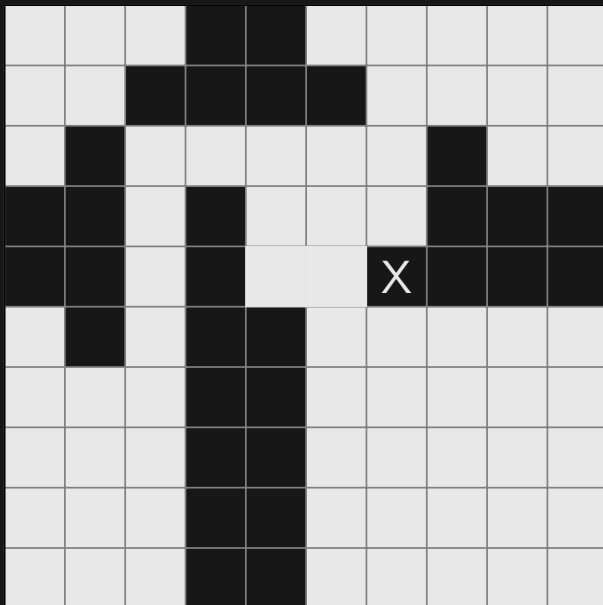
S_i gate in f_2 I



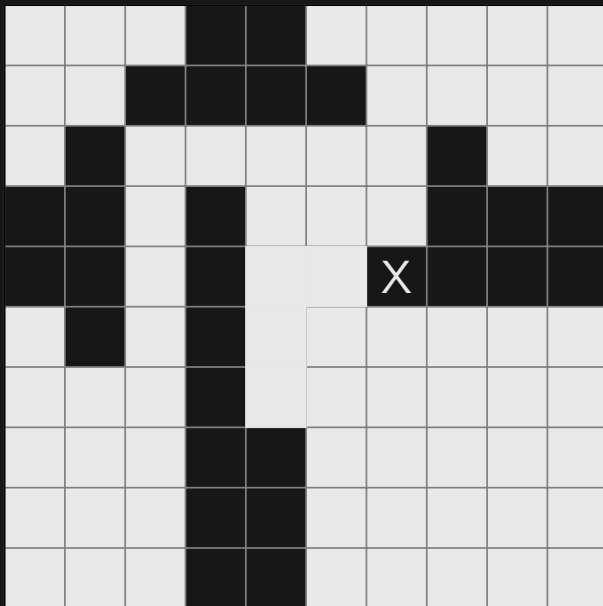
S_i gate in f_2 I



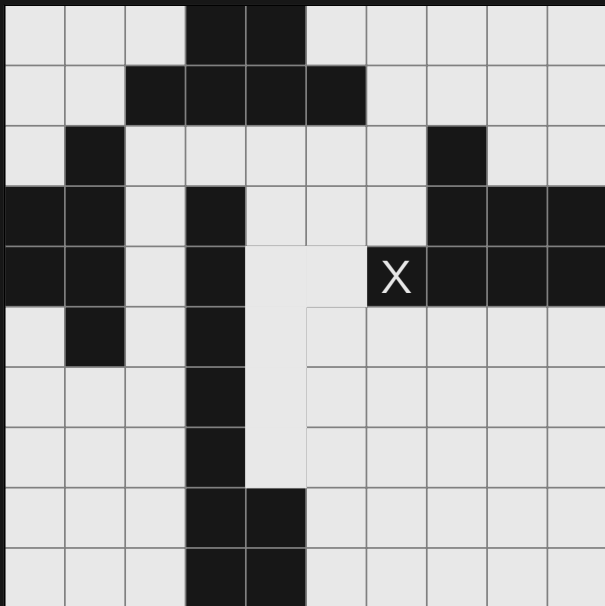
S_i gate in f_2 I



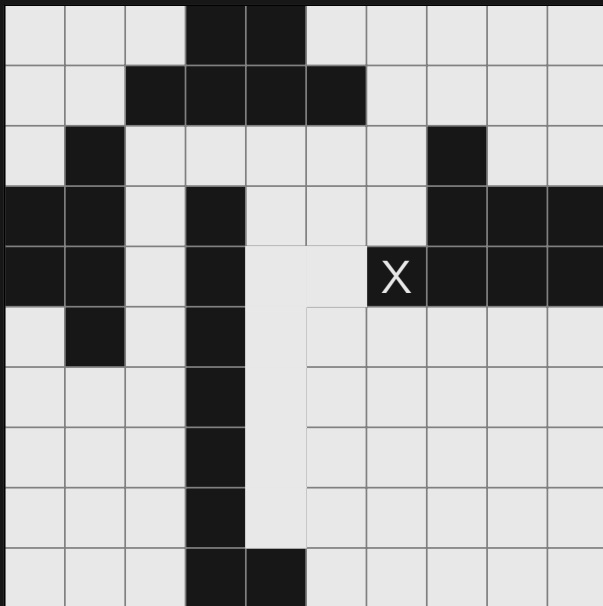
S_i gate in f_2 I



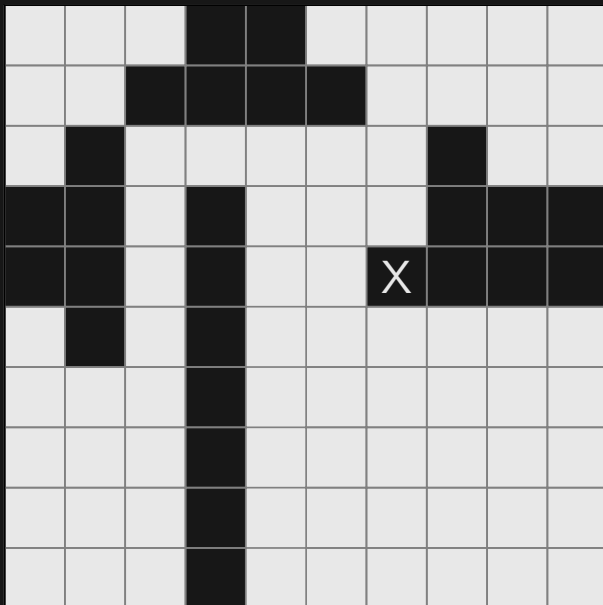
S_i gate in f_2 I



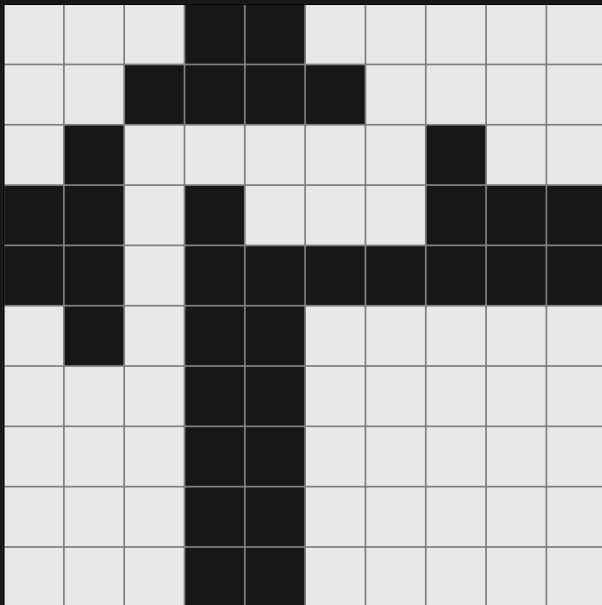
S_i gate in f_2 I



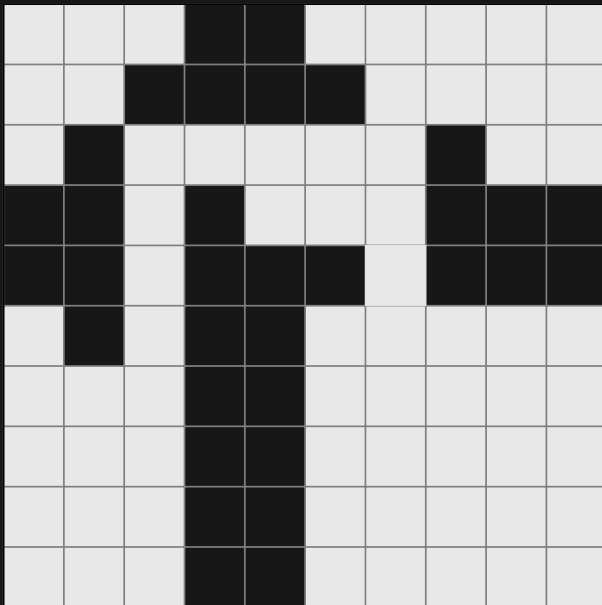
S_i gate in f_2 I



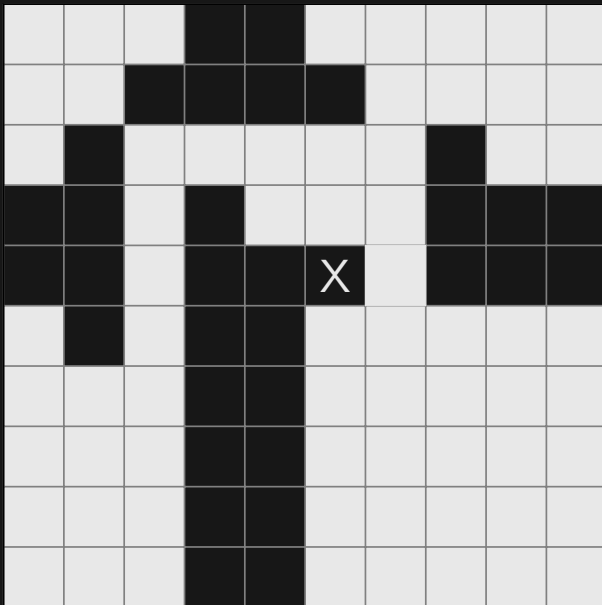
S_i gate in f_2 II



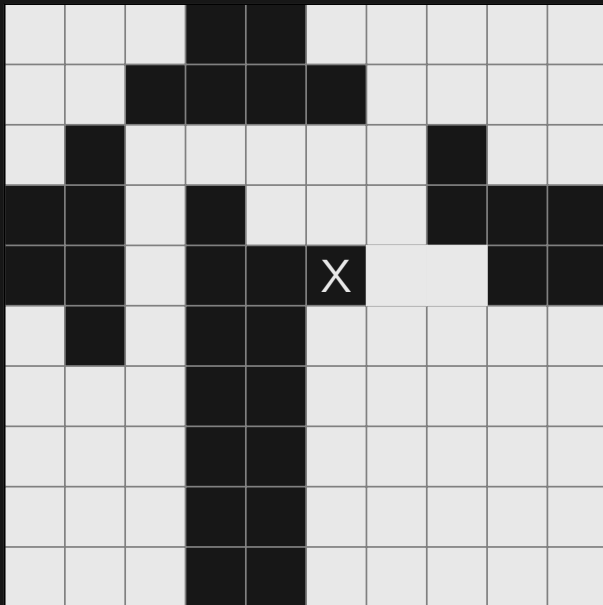
S_i gate in f_2 II



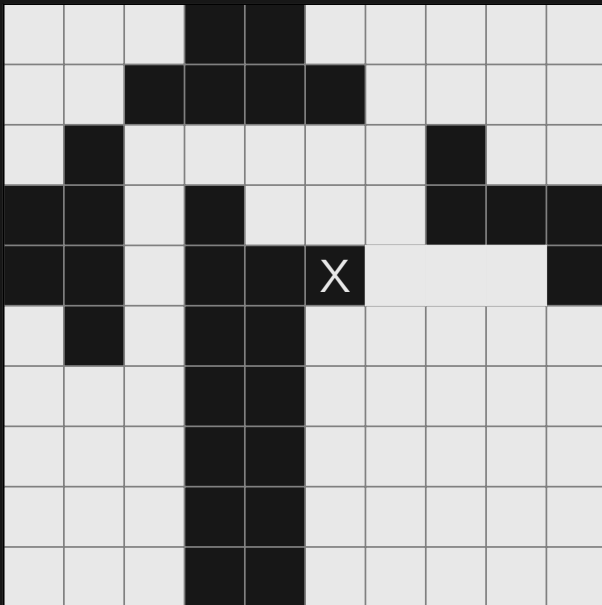
S_i gate in f_2 II



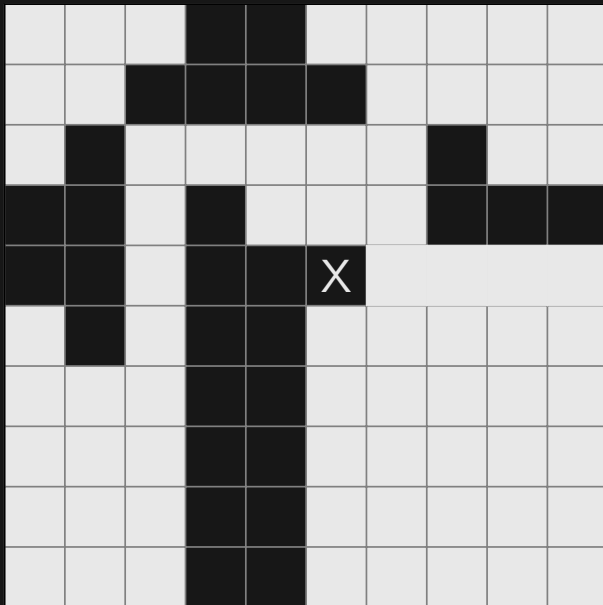
S_i gate in f_2 II



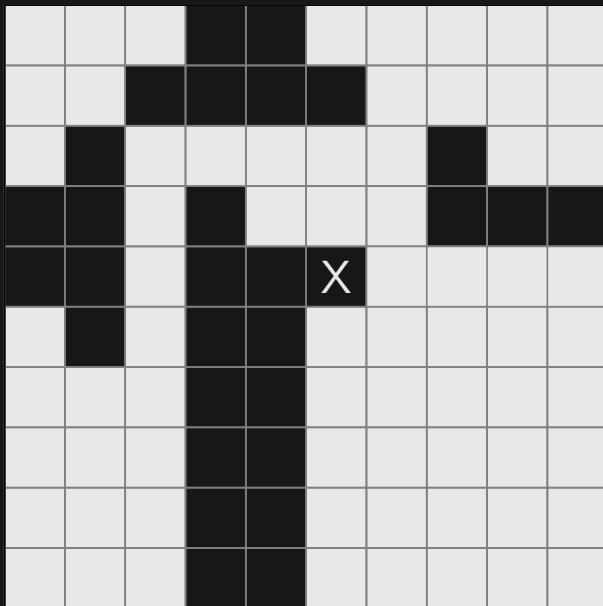
S_i gate in f_2 II



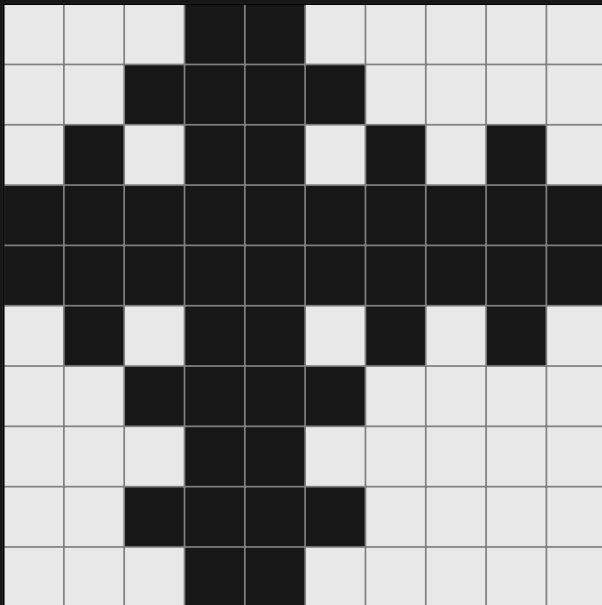
S_i gate in f_2 II



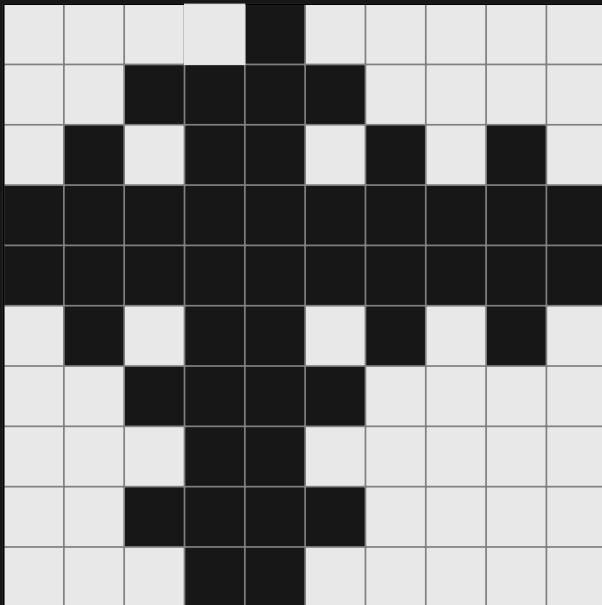
S_i gate in f_2 II



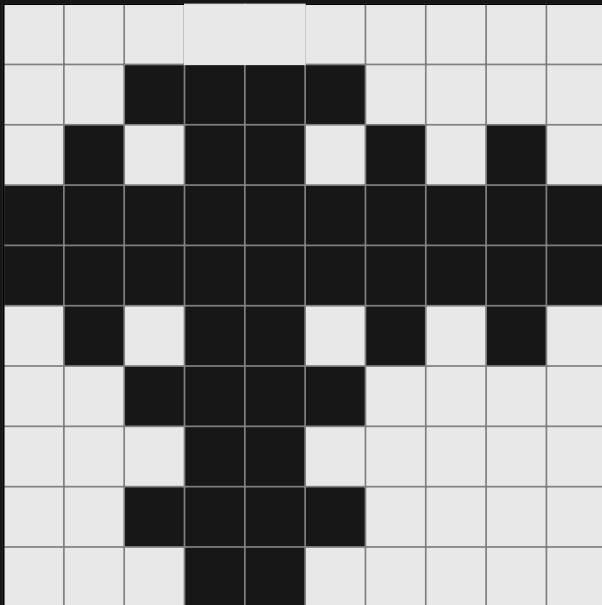
0 gate in f_2 II



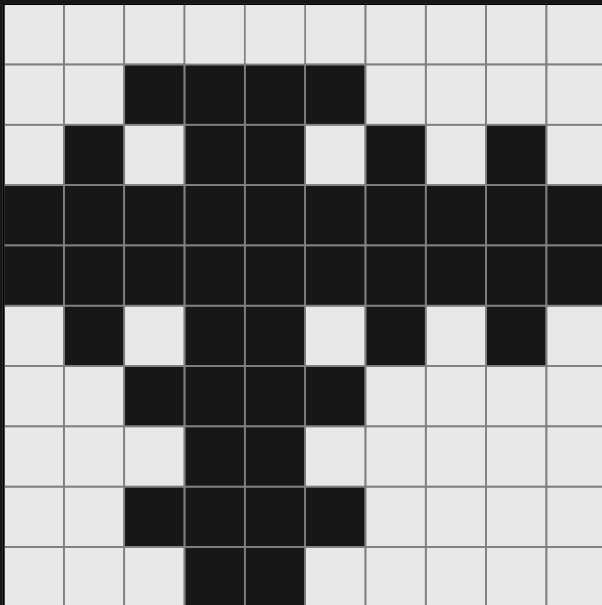
0 gate in f_2 II



0 gate in f_2 II



0 gate in f_2 II



Concluding remarks

- ▶ We have a very restrictive NP-complete problem for (A)CA
- ▶ We simple local rule with a complex behavior in synchronous and asynchronous update
- ▶ To explore the “one way ” (A)CA

Gracias!